
common-ovf-tool Documentation

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the COT project developers

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Introduction

COT (the Common OVF Tool) is a tool for editing [Open Virtualization Format](#) (.ovf, .ova) virtual appliances, with a focus on virtualized network appliances such as the [Cisco CSR 1000V](#) and [Cisco IOS XRv](#) platforms.

COT's capabilities include:

- Add a disk or other file to an OVF/OVA
- Edit OVF hardware information (CPUs, RAM, NICs, configuration profiles, etc.)
- Edit product description information in an OVF/OVA
- Edit OVF environment properties
- Display a descriptive summary of the contents of an OVA or OVF package
- Embed a bootstrap configuration text file into an OVF/OVA.
- Deploy an OVF/OVA to an ESXi (VMware vSphere or vCenter) server to provision a new virtual machine (VM).

1.1 Examples

Displaying a summary of OVA contents:

```
> cot info --brief iosxrv.5.1.1.ova
-----
iosxrv.5.1.1.ova
COT detected platform type: Cisco IOS XRv
-----
Product:  Cisco IOS XRv
Vendor:   Cisco Systems, Inc.
Version:  5.1.1

Files and Disks:      File Size  Capacity Device
-----
iosxrv.vmdk           271.59 MB   3.00 GB harddisk @ IDE 0:0

Hardware Variants:
System types:         vmx-08 Cisco:Internal:VMCloud-01
Ethernet device types: E1000

Configuration Profiles: CPUs      Memory NICs  Serials Disks/Capacity
-----
1CPU-3GB-2NIC (default)  1    3.00 GB   2      2    1 /   3.00 GB
```

2CPU-4GB-8NIC	2	4.00 GB	8	2	1 /	3.00 GB
4CPU-6GB-10NIC	4	6.00 GB	10	2	1 /	3.00 GB

Adding a custom hardware configuration profile to an OVA:

```
> cot edit-hardware csr1000v.ova --output csr1000v_custom.ova \  
    --profile 1CPU-4GB --cpus 1 --memory 4GB
```

Customizing OVF environment properties:

```
> cot edit-properties csr1000v.ova --output csr1000v_custom.ova \  
    --properties mgmt-ipv4-addr=10.1.1.100/24 \  
                mgmt-ipv4-gateway=10.1.1.1
```

Installing COT

2.1 System requirements

- COT requires either Python 2.7 or Python 3.2 or later.
- COT is tested to work under Mac OS X and Ubuntu Linux and similar distros.
- COT now has limited support for CentOS and Python 2.6 as well.
- Certain COT features require helper programs - these will typically be installed automatically when installing COT:
 - COT uses [qemu-img](#) as a helper program for various operations involving the creation, inspection, and modification of hard disk image files packaged in an OVF.
 - The `cot add-disk` command requires either [qemu-img](#) (version 2.1 or later) or [vmdktool](#) as a helper program when adding hard disks to an OVF.
 - The `cot inject-config` command requires [mkisofs](#) to create ISO (CD-ROM) images and/or [fatdisk](#) to create hard disk images.
 - The `cot deploy ... esxi` command requires [ovftool](#) to communicate with an ESXi server. If [ovftool](#) is installed, COT's automated unit tests will also make use of [ovftool](#) to perform additional verification that OVFs and OVAs created by COT align with VMware's expectations for these file types.

2.2 Mac OS X installation

The recommended installation method on Mac OS X is to use [MacPorts](#). Once you have MacPorts set up on your system, all you have to do is:

```
sudo port install cot
```

Optionally, download [ovftool](#) from VMware and install it. (VMware requires a site login to download [ovftool](#), which is the only reason I haven't automated this too...)

2.3 Linux installation

The simplest installation path (assuming you have Python 2.6 or later and Git installed already) is as follows:

```
git clone git://github.com/glenmmatthews/cot
cd cot
python ./setup.py build
sudo python ./setup.py install
```

If you can't install or use Git for whatever reason, you can download via HTTP instead:

```
wget -O cot.tgz https://github.com/glenmmatthews/cot/archive/master.tar.gz
tar xzf cot.tgz
cd cot-master
python setup.py build
sudo python setup.py install
```

The specifics may vary depending on your Linux distribution, of course. For more details, see [Linux installation in detail](#).

2.3.1 Linux installation in detail

Detailed installation instructions for Linux if the basic instructions from *Installing COT* are insufficient.

- [Check installed Python version](#)
- [Download COT](#)
 - [Downloading COT via HTTP](#)
 - [Downloading COT via Git](#)
- [Build COT](#)
- [Install helper programs](#)
 - [Install qemu-img](#)
 - [Install vmdktool \(if needed\)](#)
 - [Install fatdisk \(optional\)](#)
 - [Install mkisofs or genisoimage \(optional\)](#)
 - [Install ovftool \(optional\)](#)
- [Install COT](#)

Check installed Python version

Make sure your Python version is ideally at least 2.7 or 3.2:

```
> python --version
Python 2.7.4
```

CentOS in particular defaults to Python 2.6 - COT can be installed and run under Python 2.6 but this is not optimal. See below for more details.

Download COT

You can download COT via either HTTP or via Git.

Downloading COT via HTTP

To download the latest bleeding-edge version:

```
wget -O cot.tgz https://github.com/glennmatthews/cot/archive/master.tar.gz
tar xzf cot.tgz
cd cot-master
```

To download a specific stable release (in this example, v1.2.1):

```
wget -O cot.tgz https://github.com/glennmatthews/cot/archive/v1.2.1.tar.gz
tar xzf cot.tgz
cd cot-1.2.1
```

Downloading COT via Git

Under Ubuntu and similar, you may need to run `sudo apt-get install git`. Under CentOS and similar, you may need to run `sudo yum install git`.

Make a local clone of the Git repository:

```
git clone git://github.com/glennmatthews/cot
cd cot
```

This will default to the latest bleeding-edge version. If you want a specific stable release, use the following command to select to the desired release (for example, version 1.2.1):

```
git checkout tags/v1.2.1
```

Build COT

While you can run COT directly from this directory (`./bin/cot ...`), you can also use the included `setup.py` script to install the COT modules and scripts as part of your system Python environment. In that case, build and test COT as follows:

```
> python ./setup.py check
running check
> python ./setup.py build
running build
running build_py
```

Install helper programs

Once you have verified your Python version, run the following command to check for and install the various helper programs COT relies upon.

```
sudo python ./setup.py install_helpers
```

If any helpers are missing, the script will warn you and give you an option to attempt to automatically install them. If it tries and fails to do so, it will point you to the web site for the failed tool - but *please* post an issue on GitHub (<https://github.com/glennmatthews/cot/issues>) so that we can identify the failure and work to improve this script.

If for some reason you do not wish to use the above script, or would like to understand exactly what it's doing, see the following sections:

- Install `qemu-img`
- Install `vmtoolsd` (if needed)
- Install `fatdisk` (optional)
- Install `mkisofs` or `genisoimage` (optional)
- Install `ovftool` (optional)

In any case, once the helper tools you need are installed, you can proceed to [Install COT](#).

Install `qemu-img`

- Ubuntu and similar: `sudo apt-get install qemu`
- CentOS and similar: `sudo yum install qemu-img`

See http://en.wikibooks.org/wiki/QEMU/Installing_QEMU for other Linux variants.

Install `vmtoolsd` (if needed)

First, check your QEMU version to see if you even need `vmtoolsd`:

```
$ qemu-img --version | grep " version"
qemu-img version 2.1.0, Copyright (c) 2004-2008 Fabrice Bellard
```

If the reported version is 2.1.0 or newer, you don't need `vmtoolsd`. If you have an older QEMU version and do need `vmtoolsd`:

1. Install `make` and the library `zlib` that `vmtoolsd` depends on:
 - Ubuntu and similar: `sudo apt-get install make,sudo apt-get install zlib1g-dev`
 - CentOS and similar: `sudo yum install make,sudo yum install zlib-devel`

2. Download the latest source distribution from <http://people.freebsd.org/~brian/vmtoolsd/>:

```
wget http://people.freebsd.org/~brian/vmtoolsd/vmtoolsd-1.4.tar.gz
```

3. Compile `vmtoolsd`:

```
tar xzf vmtoolsd-1.4.tar.gz
cd vmtoolsd-1.4/
make CFLAGS="-D_GNU_SOURCE"
```

4. Install `vmtoolsd`:

```
sudo mkdir -p /usr/local/man/man8
sudo make install
```

Install `fatdisk` (optional)

You only need `fatdisk` if you are planning to use `cot inject-config` to inject bootstrap configuration for a platform that requires a hard disk image rather than a CD-ROM image for its bootstrap disk. Currently the only such platform known to COT is Cisco IOSv.

1. Download the latest source distribution.

```
git clone git://github.com/goblinhack/fatdisk
cd fatdisk
```

or (if you didn't install git or it is blocked for you)

```
wget -O fatdisk.tgz https://github.com/goblinhack/fatdisk/archive/master.tar.gz
tar xzf fatdisk.tgz
cd fatdisk-master
```

2. Compile fatdisk

```
./RUNME
```

3. Install the fatdisk binary to somewhere in your \$PATH, for example:

```
sudo cp ./fatdisk /usr/local/bin/fatdisk
```

Install mkisofs or genisoimage (optional)

`mkisofs` or the similar `genisoimage` are standard on most Linux distributions. These are used by COT primarily for creation of ISO images as part of the `cot inject-config` command for various platforms, so if you are not using that command, these tools are optional.

- Ubuntu and similar: `sudo apt-get install genisoimage`
- CentOS and similar: `sudo yum install genisoimage`
- Others: <http://cdrecord.org/>

Install ovftool (optional)

If you want to validate OVF's against VMware's expectations, or if you want to use the `cot deploy esxi` command, you need `ovftool`. Otherwise it is not required.

If desired, you can download `ovftool` from <https://www.vmware.com/support/developer/ovf/> This will require creating a user account for VMware.com if you do not have one already. Once downloaded, install it according to the included instructions.

Install COT

1. Before installing COT, if you want to, you can run its built-in unit tests as follows:

```
> python ./setup.py test
running test
```

(verbose test case output omitted here for brevity)

```
-----
Ran 136 tests in 41.130s
```

```
OK
```

Note that under Python 2.6 (i.e., CentOS) this test will report numerous test skips at present as the XML generated by Python 2.6 is structured differently (but still valid!) from the XML generated by 2.7 and later, and the unit tests do not presently support this variance.

If any tests fail, likely due to missing optional dependencies described above, the failures will be reported here, giving you a chance to fix them or ignore them before installing COT.

2. Install COT:

```
> sudo python ./setup.py install
Password:
running install
```

(verbose install output omitted)

```
Installing cot script to /usr/local/bin
```

```
Installed /usr/local/lib/python2.7/dist-packages/common_ovf_tool-1.2.1-py2.7.egg
Processing dependencies for common-ovf-tool==1.2.1
Finished processing dependencies for common-ovf-tool==1.2.1
> which cot
/usr/local/bin/cot
```

(the specific installation path will depend on your OS and system)

```
> cot -h
usage:
  cot --help
  cot --version
  cot <command> --help
  cot [-f] [-v] <command> <options>
```

```
Common OVF Tool (COT), version 1.2.1
Copyright (C) 2013-2015 the COT project developers
A tool for editing Open Virtualization Format (.ovf, .ova) virtual appliances,
with a focus on virtualized network appliances such as the Cisco CSR 1000V and
Cisco IOS XRv platforms.
...
```

Optionally, download [ovftool](#) from VMware and install it. (VMware requires a site login to download ovftool, which is the only reason I haven't automated this too...)

Using COT

3.1 Getting CLI help

You can always get detailed help for COT by running `cot --help`, `cot <command> --help`, or `cot help <command>`.

```
> cot --help
usage:
  cot --help
  cot --version
  cot help <command>
  cot <command> --help
  cot <options> <command> <command-options>
```

Common OVF Tool (COT), version 1.2.1
 Copyright (C) 2013-2015 the COT project developers.
 A tool for editing Open Virtualization Format (.ovf, .ova) virtual appliances, with a focus on virtualized network appliances such as the Cisco CSR 1000V and Cisco IOS XRv platforms.

optional arguments:

```
-h, --help          show this help message and exit
-V, --version       show program's version number and exit
-f, --force         Perform requested actions without prompting for
                    confirmation
-q, --quiet         Quiet output and logging (warnings and errors only)
-v, --verbose       Verbose output and logging
-vv, -d, --debug    Debug (most verbose) output and logging
```

commands:

```
<command>
  add-disk          Add a disk image to an OVF package and map it as a
                    disk in the guest environment
  add-file          Add a file to an OVF package
  deploy            Create a new VM on the target hypervisor from the
                    given OVF
  edit-hardware     Edit virtual machine hardware properties of an OVF
  edit-product      Edit product info in an OVF
  edit-properties   Edit environment properties of an OVF
  info              Generate a description of an OVF package
  inject-config     Inject a configuration file into an OVF package
  help              Print help for a command
```

Note: some subcommands rely on external software tools, including:

- * qemu-img (<http://www.qemu.org/>)
- * mkisofs (<http://cdrecord.org/>)
- * ovftool (<https://www.vmware.com/support/developer/ovf/>)
- * fatdisk (<http://github.com/goblinhack/fatdisk>)
- * vmdktool (<http://www.freshports.org/sysutils/vmdktool/>)

3.2 Inspecting OVF contents with `cot info`

```
> cot info -h
```

usage:

```
    cot info --help
    cot info [-b | -v] PACKAGE [PACKAGE ...]
```

Show a summary of the contents of the given OVF(s) and/or OVA(s).

positional arguments:

```
    PACKAGE [PACKAGE ...]
                        OVF descriptor(s) and/or OVA file(s) to describe
```

optional arguments:

```
    -h, --help          show this help message and exit
    -b, --brief          Brief output (shorter)
    -v, --verbose        Verbose output (longer)
```

3.3 Updating version information with `cot edit-product`

```
> cot edit-product --help
```

usage:

```
    cot edit-product --help
    cot <opts> edit-product PACKAGE [-o OUTPUT] [-v SHORT_VERSION]
                                   [-V FULL_VERSION]
```

Edit product information attributes of the given OVF or OVA

positional arguments:

```
    PACKAGE              OVF descriptor or OVA file to edit
```

optional arguments:

```
    -h, --help          show this help message and exit
    -o OUTPUT, --output OUTPUT
                        Name/path of new OVF/OVA package to create instead
                        of updating the existing OVF
    -v SHORT_VERSION, --version SHORT_VERSION
                        Software short version string, such as "15.3(4)S"
                        or "5.2.0.01I"
    -V FULL_VERSION, --full-version FULL_VERSION
                        Software long version string, such as "Cisco IOS-
                        XE Software, Version 15.3(4)S"
```

3.4 Adding disks to an OVF with `cot add-disk`

```
> cot add-disk --help
usage:
  cot add-disk --help
  cot <opts> add-disk DISK_IMAGE PACKAGE [-o OUTPUT] [-f FILE_ID]
                                     [-t {harddisk,cdrom}] [-c {ide,scsi}] [-s SUBTYPE]
                                     [-a ADDRESS] [-d DESCRIPTION] [-n DISKNAME]
```

Add or replace a disk image in the specified OVF or OVA. If the specified disk image, controller/address, file-id, and/or instance match an existing entry in the OVF, will replace the existing disk with the provided file (prompting for confirmation if `--force` was not set); otherwise, will create a new disk entry.

positional arguments:

DISK_IMAGE	Disk image file to add to the package
PACKAGE	OVF descriptor or OVA file to edit

general options:

<code>-h, --help</code>	Show this help message and exit
<code>-o OUTPUT, --output OUTPUT</code>	Name/path of new OVF/OVA package to create instead of updating the existing OVF

disk-related options:

<code>-f FILE_ID, --file-id FILE_ID</code>	Disk image file ID string within the OVF package (default: use disk image filename)
<code>-t {harddisk,cdrom}, --type {harddisk,cdrom}</code>	Disk type (default: files ending in .vmdk/.raw/.qcow2/.img will use harddisk and files ending in .iso will use cdrom)

controller-related options:

<code>-c {ide,scsi}, --controller {ide,scsi}</code>	Disk controller type (default: determined by disk type and platform)
<code>-a ADDRESS, --address ADDRESS</code>	Address of the disk, such as "1:0". Requires that <code>--controller</code> be explicitly set. (default: use first unused address on the controller)
<code>-s SUBTYPE, --subtype SUBTYPE</code>	Disk controller subtype such as "virtio" or "lsilogic".

descriptive options:

<code>-d DESCRIPTION, --description DESCRIPTION</code>	Description of this disk (optional)
<code>-n DISKNAME, --name DISKNAME</code>	Name of this disk (default: "Hard disk #" or "CD-ROM #" as appropriate)

3.5 Packaging additional files into an OVF with `cot add-file`

```
> cot add-file --help
usage:
  cot add-file --help
  cot <opts> add-file FILE PACKAGE [-o OUTPUT] [-f FILE_ID]
```

Add or replace a file in the given OVF. If the specified file and/or file-id match existing package contents, will replace it (prompting for confirmation if `--force` was not set); otherwise, will create a new file entry.

positional arguments:

FILE	File to add to the package
PACKAGE	Package, OVF descriptor or OVA file to edit

optional arguments:

-h, --help	show this help message and exit
-o OUTPUT, --output OUTPUT	Name/path of new VM package to create instead of updating the existing package
-f FILE_ID, --file-id FILE_ID	File ID string within the package (default: same as filename)

3.6 Customizing hardware profiles with `cot edit-hardware`

```
> cot edit-hardware --help
usage:
  cot edit-hardware --help
  cot <opts> edit-hardware PACKAGE [-o OUTPUT] -v TYPE [TYPE2 ...]
  cot <opts> edit-hardware PACKAGE [-o OUTPUT] [-p PROFILE [PROFILE2 ...]]
    [-c CPUS] [-m MEMORY] [-n NICS]
    [--nic-type {e1000,virtio,vmxnet3}]
    [-N NETWORK [NETWORK2 ...]] [-M MAC1 [MAC2 ...]]
    [--nic-names NAME1 [NAME2 ...]] [-s SERIAL_PORTS]
    [-S URI1 [URI2 ...]]
    [--scsi-subtype SCSI_SUBTYPE]
    [--ide-subtype IDE_SUBTYPE]
```

Edit hardware properties of the specified OVF or OVA

positional arguments:

PACKAGE	OVF descriptor or OVA file to edit
---------	------------------------------------

general options:

-h, --help	Show this help message and exit
-o OUTPUT, --output OUTPUT	Name/path of new OVF/OVA package to create instead of updating the existing OVF
-v TYPE [TYPE2 ...], --virtual-system-type TYPE [TYPE2 ...]	Change virtual system type(s) supported by this OVF/OVA package.
-p PROFILE [PROFILE2 ...], --profiles PROFILE [PROFILE2 ...]	Make hardware changes only under the given

configuration profile(s). (default: changes apply to all profiles)

computational hardware options:

-c CPUS, --cpus CPUS Set the number of CPUs.
 -m MEMORY, --memory MEMORY
 Set the amount of RAM. (Examples: "4096MB", "4GB")

network interface options:

-n NICS, --nics NICS Set the number of NICs.
 --nic-type {e1000,virtio,vmxnet3}
 Set the hardware type for all NICs. (default: do not change existing NICs, and new NICs added will match the existing type.)
 -N NETWORK [NETWORK2 ...], --nic-networks NETWORK [NETWORK2 ...]
 Specify a series of one or more network names to map NICs to. If N network names are specified, the first (N-1) NICs will be mapped to the first (N-1) networks and all remaining NICs will be mapped to the Nth network.
 -M MAC1 [MAC2 ...], --mac-addresses-list MAC1 [MAC2 ...]
 Specify a list of MAC addresses for the NICs. If N MACs are specified, the first (N-1) NICs will receive the first (N-1) MACs, and all remaining NICs will receive the Nth MAC
 --nic-names NAME1 [NAME2 ...]
 Specify a list of one or more NIC names or patterns to apply to NIC devices. If N names/patterns are specified, the first (N-1) NICs will receive the first (N-1) names and remaining NICs will be named based on the name or pattern of the Nth item. See examples.

serial port options:

-s SERIAL_PORTS, --serial-ports SERIAL_PORTS
 Set the number of serial ports.
 -S URI1 [URI2 ...], --serial-connectivity URI1 [URI2 ...]
 Specify a series of connectivity strings (URIs such as "telnet://localhost:9101") to map serial ports to. If fewer URIs than serial ports are specified, the remaining ports will be unmapped.

disk and disk controller options:

--scsi-subtype SCSI_SUBTYPE
 Set resource subtype (such as "lsilogic" or "virtio") for all SCSI controllers. If an empty string is provided, any existing subtype will be removed.
 --ide-subtype IDE_SUBTYPE
 Set resource subtype (such as "virtio") for all IDE controllers. If an empty string is provided, any existing subtype will be removed.

Examples:

```
cot edit-hardware csr1000v.ova --output csr1000v_custom.ova \
  --profile 1CPU-4GB --cpus 1 --memory 8GB
Create a new profile named "1CPU-8GB" with 1 CPU and 8 gigabytes of RAM
```

```
cot edit-hardware input.ova -o output.ova --nic-names "mgmt" "eth{0}"
    Rename the NICs in the output OVA as 'mgmt', 'eth0', 'eth1', 'eth2'...
```

```
cot edit-hardware input.ova -o output.ova --nic-names "Ethernet0/{10}"
    Rename the NICs in the output OVA as 'Ethernet0/10', 'Ethernet0/11',
    'Ethernet0/12', etc.
```

3.7 Customizing OVF environment settings with cot edit-properties

```
> cot edit-properties --help
```

usage:

```
cot edit-properties --help
cot <opts> edit-properties PACKAGE -p KEY1=VALUE1 [KEY2=VALUE2 ...]
    [-o OUTPUT]
cot <opts> edit-properties PACKAGE -c CONFIG_FILE [-o OUTPUT]
cot <opts> edit-properties PACKAGE [-o OUTPUT]
```

Configure environment properties of the given OVF or OVA. The user may specify key-value pairs as command-line arguments or may provide a config-file to read from. If neither are specified, the program will run interactively.

positional arguments:

PACKAGE OVF descriptor or OVA file to edit

general options:

-h, --help Show this help message and exit
-o OUTPUT, --output OUTPUT Name/path of new OVF/OVA package to create instead
 of updating the existing OVF

property setting options:

-c CONFIG_FILE, --config-file CONFIG_FILE
 Read configuration CLI from this text file and
 generate generic properties for each line of CLI
-p KEY1=VALUE1 [KEY2=VALUE2 ...], --properties KEY1=VALUE1 [KEY2=VALUE2 ...]
 Set the given property key-value pair(s). This
 argument may be repeated as needed to specify
 multiple properties to edit.

3.8 Embedding bootstrap configuration with cot inject-config

```
> cot inject-config -h
```

usage:

```
cot inject-config --help
cot <opts> inject-config PACKAGE -c CONFIG_FILE [-o OUTPUT]
cot <opts> inject-config PACKAGE -s SECONDARY_CONFIG_FILE [-o OUTPUT]
cot <opts> inject-config PACKAGE -c CONFIG_FILE -s SECONDARY_CONFIG_FILE
    [-o OUTPUT]
```

Add one or more "bootstrap" configuration file(s) to the given OVF or OVA.

positional arguments:

PACKAGE Package, OVF descriptor or OVA file to edit

optional arguments:

-h, --help show this help message and exit
 -o OUTPUT, --output OUTPUT Name/path of new VM package to create instead of updating the existing package
 -c CONFIG_FILE, --config-file CONFIG_FILE Primary configuration text file to embed
 -s SECONDARY_CONFIG_FILE, --secondary-config-file SECONDARY_CONFIG_FILE Secondary configuration text file to embed (currently only supported in IOS XRv for admin config)

3.9 Deploying an OVF to create a VM with `cot deploy`

```
> cot deploy --help
```

usage:

```
cot deploy --help
cot <opts> deploy PACKAGE esxi ...
```

Deploy a virtual machine to a specified server.

positional arguments:

PACKAGE OVF descriptor or OVA file

hypervisors supported:

esxi Deploy to ESXi, vSphere, or vCenter

optional arguments:

-h, --help show this help message and exit

3.9.1 Creating a VM on VMware vCenter/vSphere with `cot deploy esxi`

```
> cot deploy PACKAGE esxi --help
```

usage:

```
cot deploy PACKAGE esxi --help
cot <opts> deploy PACKAGE esxi LOCATOR [-u USERNAME] [-p PASSWORD]
                                     [-c CONFIGURATION] [-n VM_NAME] [-P]
                                     [-N OVF1=HOST1 [-N OVF2=HOST2 ...]]
                                     [-d DATASTORE] [-o=OVFTOOL_ARGS]
```

Deploy OVF/OVA to ESXi/vCenter/vSphere hypervisor

positional arguments:

LOCATOR vSphere target locator. Examples: "192.0.2.100"
 (deploy directly to ESXi server),
 "192.0.2.101/mydatacenter/host/192.0.2.100"
 (deploy via vCenter server)

optional arguments:

-h, --help show this help message and exit
 -u USERNAME, --username USERNAME Server login username

-p PASSWORD, --password PASSWORD
Server login password

-c CONFIGURATION, --configuration CONFIGURATION
Use the specified configuration profile defined in the OVF. If unspecified and the OVF has multiple profiles, the user will be prompted or the default configuration will be used.

-n VM_NAME, --vm-name VM_NAME
Name to use for the VM (if applicable) and any files created. If unspecified, the name of the OVF will be used.

-P, --power-on
Power on the created VM to begin booting immediately.

-N OVF_NET1=HOST_NET1 [OVF_NET2=HOST_NET2 ...]
Map networks named in the OVF to networks (bridges, vSwitches, etc.) in the hypervisor environment. This argument may be repeated as needed to specify multiple mappings.

-d DATASTORE, -ds DATASTORE, --datastore DATASTORE
ESXi datastore to use for the new VM

-o OVFTOOL_ARGS, --ovftool-args OVFTOOL_ARGS
Quoted string describing additional CLI parameters to pass through to "ovftool". Examples:
-o="--foo", --ovftool-args="--foo --bar"

Examples:

```
cot deploy foo.ova esxi 192.0.2.100 -u admin -p admin -n test_vm
  Deploy to vSphere/ESXi server 192.0.2.100 with credentials admin/admin,
  creating a VM named 'test_vm' from foo.ova.
```

```
cot deploy foo.ova esxi 192.0.2.100 -u admin -c 1CPU-2.5GB
  Deploy to vSphere/ESXi server 192.0.2.100, with username admin
  (prompting the user to input a password at runtime), creating a VM
  based on profile '1CPU-2.5GB' in foo.ova.
```

```
cot deploy foo.ova esxi "192.0.2.100/mydc/host/192.0.2.1" \
  -u administrator -N "GigabitEthernet1=VM Network" \
  -N "GigabitEthernet2=myvswitch"
  Deploy to vSphere server 192.0.2.1 which belongs to datacenter 'mydc'
  on vCenter server 192.0.2.100, and map the two NIC networks to
  vSwitches. Note that in this case -u specifies the vCenter login
  username.
```

```
cot deploy foo.ova esxi 192.0.2.100 -u admin -p password \
  --ovftool-args="--overwrite --acceptAllEulas"
  Deploy with passthrough arguments to ovftool.
```

Contributing to COT

Please do contribute! We only have a few simple requirements for diffs and pull requests.

- Follow coding guidelines
- Add automated unit tests
- Update documentation
- Add yourself as a contributor

4.1 Follow coding guidelines

4.1.1 Logging level usage

ERROR Something is wrong (such as a violation of the OVF specification) but COT was able to attempt to recover. If recovery is not possible, you should raise an `Error` of appropriate type instead of logging an **ERROR** message.

WARNING Something unexpected or risky happened that the user needs a heads-up about. This includes cases where the software had to make an uncertain choice on its own due to lack of information from the user.

INFO Important status updates about normal operation of the software. As this is the lowest logging level enabled by default, you should keep the logs generated at this level relatively brief but meaningful.

VERBOSE Detailed information of interest to an advanced or inquisitive user.

DEBUG Highly detailed information only useful to a developer familiar with the code.

4.1.2 Coding style

To verify that your code meets applicable Python coding standards, use `flake8` (`pip install flake8`):

```
cot/$ flake8
./COT/tests/ovf.py:180:80: E501 line too long (80 > 79 characters)
./COT/tests/ovf.py:184:77: F841 local variable 'ovf' is assigned to but never used
./COT/tests/ovf.py:184:80: E501 line too long (80 > 79 characters)
./COT/tests/ovf.py:196:40: F841 local variable 'ova' is assigned to but never used
./COT/tests/ovf.py:210:75: F841 local variable 'ovf' is assigned to but never used
./COT/ovf.py:776:5: E303 too many blank lines (2)
```

Fix any errors it reports, and run again until no errors are reported.

4.2 Add automated unit tests

Whether adding new functionality or fixing a bug, **please** add appropriate unit test case(s) under `COT/tests/` to cover your changes. Your changes **must** pass all existing and new automated test cases before your code will be accepted.

You can run the COT automated tests under a single Python version by running `python ./setup.py test`.

For full testing under all supported versions as well as verifying code coverage for your tests, you should install `tox` (pip install tox) and `coverage` (pip install coverage) then run `tox` from the COT directory:

```
cot/$ tox
...
py26 runtests: commands[0] | coverage run --append setup.py test --quiet
...
py27 runtests: commands[0] | coverage run --append setup.py test --quiet
...
py32 runtests: commands[0] | coverage run --append setup.py test --quiet
...
py33 runtests: commands[0] | coverage run --append setup.py test --quiet
...
py34 runtests: commands[0] | coverage run --append setup.py test --quiet
...
pypy runtests: commands[0] | coverage run --append setup.py test --quiet
...
stats runtests: commands[0] | coverage combine
stats runtests: commands[1] | coverage report -i
Name                               Stmts   Miss  Cover
-----
COT/__init__.py                     4        0   100%
COT/add_disk.py                    147        1    99%
COT/add_file.py                     50        0   100%
COT/cli.py                          143        6    96%
COT/data_validation.py              69        0   100%
COT/deploy.py                      142        5    96%
COT/edit_hardware.py               159        0   100%
COT/edit_product.py                 36        0   100%
COT/edit_properties.py             104       40    62%
COT/helper_tools.py                171        3    98%
COT/info.py                        41        0   100%
COT/inject_config.py               87        2    98%
COT/ovf.py                         1586       52    96%
COT/platforms.py                   173        0   100%
COT/submodule.py                    80        2    98%
COT/ui_shared.py                    24        0   100%
COT/vm_context_manager.py           12        0   100%
COT/vm_description.py              119        1    99%
COT/vm_factory.py                   25        0   100%
COT/xml_file.py                     112        0   100%
-----
TOTAL                               3284      112    96%
stats runtests: commands[2] | coverage html -i
...
flake8 runtests: commands[0] | flake8
_____ summary _____
clean: commands succeeded
py26: commands succeeded
py27: commands succeeded
```

```
py32: commands succeeded
py33: commands succeeded
py34: commands succeeded
pypy: commands succeeded
stats: commands succeeded
flake8: commands succeeded
congratulations :)
```

After running `tox` you can check the code coverage details by opening `htmlcov/index.html` in a web browser.

4.3 Update documentation

If you add or change any COT CLI or APIs, or add or remove any external dependencies, please update the relevant documentation.

4.4 Add yourself as a contributor

If you haven't contributed to COT previously, be sure to add yourself as a contributor in the `COPYRIGHT.txt` file.

Credits

We would like to thank:

- For evangelization, user feedback and bug reports:
 - Mark Coverdill
 - Jonathan Muslow
 - Rick Ogg
 - David Rosenfeld
 - Perumal Venkatesh
- For initial design review and comments:
 - Andy Dalton
 - Jusheng Feng
 - Doug Gordon
 - Lina Long
 - Neil McGill
 - Vinod Pandarinathan
 - Rich Wellum
- For providing managerial support for the development and release of COT as open source:
 - Ray Romney
 - Sanjeev Tondale
 - Taskin Ucpinar
- Rich Wellum, for creating “Build, Deploy, Execute OVA” (`bdeo.sh`), the precursor to COT.
- Neil McGill, for creating and maintaining `fatdisk`
- Brian Somers, for creating and maintaining `vmdktool`

COT package reference

The below documents describe in depth the code structure and APIs of COT. These are not generally of interest to the end users of the COT script, but are provided for reference of developers wishing to integrate the COT package directly into their code. Package implementing the Common OVF Tool.

6.1 Virtual machine definition modules

<code>COT.vm_description</code>	Abstract superclass for reading, editing, and writing VMs.
<code>COT.vm_factory</code>	Factory for virtual machine objects.
<code>COT.vm_context_manager</code>	Context manager for virtual machine definitions.
<code>COT.xml_file</code>	Reading, editing, and writing XML files.
<code>COT.ovf</code>	Module for handling OVF and OVA virtual machine description files.

6.1.1 COT.vm_description module

Abstract superclass for reading, editing, and writing VMs.

<code>VMInitError</code>	Class representing errors encountered when trying to init/load a VM.
<code>VMDescription</code>	Abstract class for reading, editing, and writing VM definitions.

exception `VMInitError`

Bases: `exceptions.EnvironmentError`

Class representing errors encountered when trying to init/load a VM.

class `VMDescription` (*input_file*, *output_file=None*)

Bases: `object`

Abstract class for reading, editing, and writing VM definitions.

Variables

- **`input_file`** – The file this VM description was initialized from.
- **`working_dir`** – A temporary directory for storage of files.
- **`output_file`** – The file this VM description will be written to.

`add_controller_device` (*type*, *subtype*, *address*, *ctrl_item=None*)

Create a new IDE or SCSI controller, or update existing one.

Parameters

- **type** (*str*) – 'ide' or 'scsi'
- **subtype** (*str*) – Subtype such as 'virtio' (optional)
- **address** (*int*) – Controller address such as 0 or 1 (optional)
- **ctrl_item** – Existing controller device to update (optional)

Returns New or updated controller device object

add_disk (*file_path, file_id, disk_type, disk=None*)

Add a new disk object to the VM or overwrite the provided one.

Parameters

- **file_path** (*str*) – Path to disk image file
- **file_id** (*str*) – Identifier string for the file/disk mapping
- **disk_type** (*str*) – 'harddisk' or 'cdrom'
- **disk** – Existing disk object to overwrite

Returns New or updated disk object

add_disk_device (*type, address, name, description, disk, file, ctrl_item, disk_item=None*)

Add a new disk device to the VM or update the provided one.

Parameters

- **type** (*str*) – 'harddisk' or 'cdrom'
- **address** (*str*) – Address on controller, such as "1:0" (optional)
- **name** (*str*) – Device name string (optional)
- **description** (*str*) – Description string (optional)
- **disk** – Disk object to map to this device
- **file** – File object to map to this device
- **ctrl_item** – Controller object to serve as parent
- **disk_item** – Existing disk device to update instead of making a new device.

Returns New or updated disk device object.

add_file (*file_path, file_id, file=None, disk=None*)

Add a new file object to the VM or overwrite the provided one.

Parameters

- **file_path** (*str*) – Path to file to add
- **file_id** (*str*) – Identifier string for the file in the VM
- **file** – Existing file object to overwrite
- **disk** – Existing disk object referencing *file*.

Returns New or updated file object

check_sanity_of_disk_device (*disk, file, disk_item, ctrl_item*)

Check if the given disk is linked properly to the other objects.

Parameters

- **disk** – Disk object to validate
- **file** – File object which this disk should be linked to (optional)
- **disk_item** – Disk device object which should link to this disk (optional)
- **ctrl_item** – Controller device object which should link to the `disk_item`

Raises `ValueMismatchError` if the given items are not linked properly.

`config_file_to_properties` (*file*)

Import each line of a text file into a configuration property.

Parameters **file** (*str*) – File name to import.

`convert_disk_if_needed` (*file_path*, *kind*)

Convert the disk to a more appropriate format if needed.

Parameters

- **file_path** (*str*) – Image to inspect and possibly convert
- **kind** (*str*) – Image type (harddisk/cdrom)

Returns

- `file_path`, if no conversion was required
- or a file path in `output_dir` containing the converted image

`create_configuration_profile` (*id*, *label*, *description*)

Create/update a configuration profile with the given ID.

Parameters

- **id** – Profile identifier
- **label** (*str*) – Brief descriptive label for the profile
- **description** (*str*) – Verbose description of the profile

`create_network` (*label*, *description*)

Define a new network with the given label and description.

Parameters

- **label** (*str*) – Brief label for the network
- **description** (*str*) – Verbose description of the network

`destroy` ()

Clean up after ourselves.

Deletes `self.working_dir` and its contents.

classmethod `detect_type_from_name` (*filename*)

Check the given filename to see if it looks like a type we support.

Does not check file contents, as the given filename may not yet exist.

Returns A string representing a recognized and supported type of file

Raises `ValueUnsupportedError` if we don't know how to handle this file.

`find_device_location` (*device*)

Find the controller type and address of a given device object.

Parameters **device** – Hardware device object.

Returns (type, address), such as ("ide", "1:0").

find_empty_drive (type)

Find a disk device that exists but contains no data.

Parameters type (str) – Disk type, such as 'cdrom' or 'harddisk'

Returns Hardware device object, or None.

find_open_controller (type)

Find the first open slot on a controller of the given type.

Parameters type (str) – 'ide' or 'scsi'

Returns (controller_device, address_string) or (None, None)

get_common_subtype (type)

Get the sub-type common to all devices of the given type.

Parameters type (str) – Device type such as 'ide' or 'memory'.

Returns None, if multiple such devices exist and they do not all have the same sub-type.

Returns Subtype string common to all devices of the type.

get_configuration_profile_ids ()

Get the list of supported configuration profile identifiers.

If there are no profiles defined, returns an empty list. If there is a default profile, it will be first in the list.

get_default_profile_name ()

Get the name of the default configuration profile.

Returns Profile name or None if none are defined.

get_file_ref_from_disk (disk)

Get the file reference from the given opaque disk object.

Parameters disk – Disk object to query

Returns String that can be used to identify the file associated with this disk

get_id_from_file (file)

Get the file ID from the given opaque file object.

Parameters file – File object to query

Returns Identifier string associated with this object

get_network_list ()

Get the list of network names currently defined in this VM.

Return type list[str]

get_nic_count (profile_list)

Get the number of NICs under the given profile(s).

Parameters profile_list (list) – Profile(s) of interest.

Return type dict

Returns { profile_name : nic_count }

get_path_from_file (file)

Get the file path from the given opaque file object.

Parameters file – File object to query

Returns Relative path to the file associated with this object

get_platform()

Get the Platform class object associated with this VM.

Returns Class object - `GenericPlatform` or a more-specific subclass if recognized as such.

get_property_array()

Get an array of configuration properties.

Returns Array of dicts (one per property) with the keys "key", "value", "qualifiers", "type", "label", and "description".

get_property_value(key)

Get the value of the given property.

Parameters **key** (*str*) – Property identifier

Returns Value of this property, or None

get_serial_count(profile_list)

Get the number of serial ports under the given profile(s).

Return type dict

Returns { profile_name : serial_count }

get_subtype_from_device(device)

Get the sub-type of the given opaque device object.

Parameters **device** – Device object to query

Returns None, or string such as 'virtio' or 'lsilogic'

get_type_from_device(device)

Get the type of the given opaque device object.

Parameters **device** – Device object to query

Returns string such as 'ide' or 'memory'

info_string(width=79, verbosity_option=None)

Get a descriptive string summarizing the contents of this VM.

Parameters

- **width** (*int*) – Line length to wrap to where possible.
- **verbosity_option** (*str*) – 'brief', None (default), or 'verbose'

Returns Wrapped, appropriately verbose string.

profile_info_string(width=79, verbosity_option=None, enumerate=False)

Get a string summarizing available configuration profiles.

Parameters

- **TEXT_WIDTH** (*int*) – Line length to wrap to if possible
- **verbosity_option** (*str*) – 'brief', None (default), or 'verbose'
- **enumerate** (*boolean*) – If True, number the profiles.

Returns Appropriately formatted and verbose string.

search_from_controller(controller, address)

From the controller type and device address, look for existing disk.

Parameters

- **controller** (*str*) – 'ide' or 'scsi'
- **address** (*str*) – Device address such as '1:0'

Returns (*file*, *disk*, *controller_device*, *disk_device*), opaque objects of which any or all may be None

search_from_file_id (*file_id*)

From the given file ID, try to find any existing objects.

Parameters **filename** (*str*) – Filename to search from

Returns (*file*, *disk*, *controller_device*, *disk_device*), opaque objects of which any or all may be None

search_from_filename (*filename*)

From the given filename, try to find any existing objects.

Parameters **filename** (*str*) – Filename to search from

Returns (*file*, *disk*, *controller_device*, *disk_device*), opaque objects of which any or all may be None

set_cpu_count (*cpus*, *profile_list*)

Set the number of CPUs.

Parameters

- **cpus** (*int*) – Number of CPUs
- **profile_list** (*list*) – Change only the given profiles

set_ide_subtype (*type*, *profile_list*)

Set the device subtype for the IDE controller(s).

Parameters

- **type** (*str*) – IDE subtype string
- **profile_list** (*list*) – Change only the given profiles

set_long_version (*version_string*)

Set a long string describing the product version.

Parameters **version_string** (*str*) – Long descriptive version string.

set_memory (*megabytes*, *profile_list*)

Set the amount of RAM, in megabytes.

Parameters

- **megabytes** (*int*) – Memory value, in megabytes
- **profile_list** (*list*) – Change only the given profiles

set_nic_count (*count*, *profile_list*)

Set the given profile(s) to have the given number of NICs.

Parameters

- **count** (*int*) – number of NICs
- **profile_list** (*list*) – Change only the given profiles

set_nic_mac_addresses (*mac_list*, *profile_list*)

Set the MAC addresses for NICs under the given profile(s).

Note: If the length of *mac_list* is less than the number of NICs, will use the last entry in the list for all remaining NICs.

Parameters

- **mac_list** (*list*) – List of MAC addresses to assign to NICs
- **profile_list** (*list*) – Change only the given profiles

set_nic_names (*name_list*, *profile_list*)

Set the device names for NICs under the given profile(s).

TODO: document magic expansion syntax here

Parameters

- **name_list** (*list*) – List of names to assign.
- **profile_list** (*list*) – Change only the given profiles

set_nic_networks (*network_list*, *profile_list*)

Set the NIC to network mapping for NICs under the given profile(s).

Note: If the length of *network_list* is less than the number of NICs, will use the last entry in the list for all remaining NICs.

Parameters

- **network_list** (*list*) – List of networks to map NICs to
- **profile_list** (*list*) – Change only the given profiles

set_nic_type (*type*, *profile_list*)

Set the hardware type for NICs.

Parameters

- **type** (*str*) – NIC hardware type
- **profile_list** (*list*) – Change only the given profiles.

set_output_file (*output_file*)

Validate the given output filename and save it for later use.

Parameters **output_file** (*str*) – Output filename

set_property_value (*key*, *value*)

Set the value of the given property (converting value if needed).

Parameters

- **key** (*str*) – Property identifier
- **value** – Value to set for this property

Returns the (converted) value that was set.

set_scsi_subtype (*type*, *profile_list*)

Set the device subtype for the SCSI controller(s).

Parameters

- **type** (*str*) – SCSI subtype string
- **profile_list** (*list*) – Change only the given profiles

set_serial_connectivity (*conn_list*, *profile_list*)

Set the serial port connectivity under the given profile(s).

Parameters

- **conn_list** (*list*) – List of connectivity strings
- **profile_list** (*list*) – Change only the given profiles

set_serial_count (*count*, *profile_list*)

Set the given profile(s) to have the given number of NICs.

Parameters

- **count** (*int*) – Number of serial ports
- **profile_list** (*list*) – Change only the given profiles

set_short_version (*version_string*)

Set a short string describing the product version.

Parameters **version_string** (*str*) – Short descriptive version string.

set_system_type (*type_list*)

Set the virtual system type(s) supported by this virtual machine.

Parameters **type_list** (*list*) – List of system type strings

write ()

Write the VM description to *output_file*, if any.

verbosity_options = {None: 1, 'brief': 0, 'verbose': 2}

6.1.2 COT.vm_factory module

Factory for virtual machine objects.

class VMFactory

Creates a VMDescription instance from a specified input file.

classmethod create (*input_file*, *output_file*)

Create an appropriate VMDescription subclass instance from a file.

Raises

- **VMInitError** – if no appropriate class is identified
- **VMInitError** – if the selected subclass raises a `ValueUnsupportedError` while loading the file.

Parameters

- **input_file** (*str*) – File to read VM description from
- **output_file** (*str*) – File to write to when finished (optional)

Return type instance of `VMDescription` or appropriate subclass

6.1.3 COT.vm_context_manager module

Context manager for virtual machine definitions.

class VMContextManager (*input_file, output_file*)

Context manager for virtual machine definitions.

When the context manager exits, unless an error occurred, the virtual machine's `write()` method is called. Regardless of whether an error occurred, the virtual machine's `destroy()` method is then called.

Use as follows:

```
with VMContextManager(input_file, output_file) as vm:
    vm.foo()
    vm.bar()
```

6.1.4 COT.xml_file module

Reading, editing, and writing XML files.

class XML

Bases: `object`

Class capable of reading, editing, and writing XML files.

classmethod add_child (*parent, new_child, ordering=None, known_namespaces=None*)

Add the given child element under the given parent element.

Parameters

- **parent** (*xml.etree.ElementTree.Element*) – Parent element
- **new_child** (*xml.etree.ElementTree.Element*) – Child element to attach
- **ordering** (*list*) – (Optional) List describing the expected ordering of child tags under the parent; if a new child element is created, its placement under the parent will respect this sequence.
- **known_namespaces** (*list*) – (Optional) List of well-understood XML namespaces. If a new child is created, and `ordering` is given, any tag (new or existing) that is encountered but not accounted for in `ordering` will result in COT logging a warning **iff** the unaccounted-for tag is in a known namespace.

classmethod find_all_children (*parent, tag, attrib={}*)

Find all matching child elements under the specified parent element.

Parameters

- **parent** (*xml.etree.ElementTree.Element*) – Parent element
- **tag** (*str*) – Child tag to match on
- **attrib** (*dict*) – Child attributes to match on

Return type list of `xml.etree.ElementTree.Element` instances

classmethod find_child (*parent, tag, attrib={}, required=False*)

Find the unique child element under the specified parent element.

Raises

- **LookupError** – if more than one matching child is found
- **KeyError** – if no matching child is found and `required` is `True`

Parameters

- **parent** (*xml.etree.ElementTree.Element*) – Parent element
- **tag** (*str*) – Child tag to match on
- **attrib** (*dict*) – Child attributes to match on
- **required** (*boolean*) – Whether to raise an error if no child exists

Return type `xml.etree.ElementTree.Element`

classmethod `get_ns` (*text*)

Get the namespace prefix from an XML element or attribute name.

read_xml (*xml_file*)

Read the given XML file and store it in memory.

The memory representation is available as `self.tree` and `self.root`.

Raises

- `xml.etree.ElementTree.ParseError` – if parsing fails under Python 2.7 or later
- `xml.parsers.expat.ExpatError` – if parsing fails under Python 2.6

Parameters `xml_file` (*str*) – File path to read.

register_namespace (*prefix*, *URI*)

Record a particular mapping between a namespace prefix and URI.

Parameters

- **prefix** (*str*) – Namespace prefix such as “ovf”
- **URI** (*str*) – Namespace URI such as “<http://schemas.dmtf.org/ovf/envelope/1>”

classmethod `set_or_make_child` (*parent*, *tag*, *text=None*, *attrib=None*, *ordering=None*, *known_namespaces=None*)

Update or create a child element under the specified parent element.

Parameters

- **parent** (*xml.etree.ElementTree.Element*) – Parent element
- **tag** (*str*) – Child element text tag to find or create
- **text** (*str*) – Value to set the child’s text attribute to
- **attrib** (*dict*) – Dict of child attributes to match on while searching and set in the final child element
- **ordering** (*list*) – See `add_child()`
- **known_namespaces** (*list*) – See `add_child()`

Returns New or updated child Element.

Return type `xml.etree.ElementTree.Element`

classmethod `strip_ns` (*text*)

Remove a namespace prefix from an XML element or attribute name.

write_xml (*file*)

Write pretty XML out to the given file.

Parameters `file` (*str*) – Filename to write to

xml_reindent (*parent, depth*)

Recursively add indentation to XML to make it look nice.

Parameters

- **parent** (*xml.etree.ElementTree.Element*) – Current parent element
- **depth** (*int*) – How far down the rabbit hole we have recursed. Increments by 2 for each successive level of nesting.

6.1.5 COT.ovf module

Module for handling OVF and OVA virtual machine description files.

Functions

<code>byte_count</code>	Convert an OVF-style value + multiplier into decimal byte count.
<code>byte_string</code>	Pretty-print the given bytes value.
<code>factor_bytes</code>	Convert a byte count into OVF-style bytes + multiplier.

Classes and Exceptions

<code>OVF</code>	Representation of the contents of an OVF or OVA.
<code>OVFNameHelper</code>	Helper class for <code>OVF</code> .
<code>OVFHardware</code>	Helper class for <code>OVF</code> .
<code>OVFHardwareDataError</code>	The input data used to construct an <code>OVFHardware</code> is not sane.
<code>OVFItem</code>	Helper class for <code>OVF</code> .
<code>OVFItemDataError</code>	Data to be added to an <code>OVFItem</code> conflicts with existing data.

byte_count (*base_val, multiplier*)

Convert an OVF-style value + multiplier into decimal byte count.

Inverse operation of `factor_bytes()`.

```
>>> byte_count("128", "byte * 2^20")
134217728
```

Parameters

- **base_val** (*str*) – Base value string (value of `ovf:capacity`, etc.)
- **multiplier** (*str*) – Multiplier string (value of `ovf:capacityAllocationUnits`, etc.)

Returns Number of bytes

Return type `int`

byte_string (*byte_count, base_shift=0*)

Pretty-print the given bytes value.

Parameters

- **byte_count** (*float*) – Value
- **base_shift** (*int*) – Base value of `byte_count` (0 = bytes, 1 = kB, 2 = MB, etc.)

Returns Pretty-printed byte string such as “1.00 GB”

factor_bytes (*byte_count*)

Convert a byte count into OVF-style bytes + multiplier.

Inverse operation of `byte_count()`

```
>>> factor_bytes(134217728)
('128', 'byte * 2^20')
>>> factor_bytes(134217729)
('134217729', 'byte')
```

Parameters `byte_count` (*int*) – Number of bytes

Returns (*base_val*, *multiplier*)

class OVF (*input_file*, *output_file*)

Bases: `COT.vm_description.VMDescription`, `COT.xml_file.XML`

Representation of the contents of an OVF or OVA.

Variables

- **platform** – Class object (`GenericPlatform` or a subclass thereof) that most accurately describes the virtual machine type described by this OVF.
- **ovf_version** – Float representing the OVF specification version in use. Supported values at present are 0.9, 1.0, and 2.0.

add_controller_device (*type*, *subtype*, *address*, *ctrl_item=None*)

Create a new IDE or SCSI controller, or update existing one.

Parameters

- **type** (*str*) – 'ide' or 'scsi'
- **subtype** (*str*) – Subtype such as 'virtio' (optional)
- **address** (*int*) – Controller address such as 0 or 1 (optional)
- **ctrl_item** – Existing controller device to update (optional)

Returns New or updated controller device object

add_disk (*file_path*, *file_id*, *disk_type*, *disk=None*)

Add a new disk object to the VM or overwrite the provided one.

Parameters

- **file_path** (*str*) – Path to disk image file
- **file_id** (*str*) – Identifier string for the file/disk mapping
- **disk_type** (*str*) – 'harddisk' or 'cdrom'
- **disk** – Existing disk object to overwrite

Returns New or updated disk object

add_disk_device (*type*, *address*, *name*, *description*, *disk*, *file*, *ctrl_item*, *disk_item=None*)

Create a new disk hardware device or overwrite an existing one.

Parameters

- **type** (*str*) – 'harddisk' or 'cdrom'
- **address** (*str*) – Address on controller, such as "1:0" (optional)
- **name** (*str*) – Device name string (optional)

- **description** (*str*) – Description string (optional)
- **disk** – Disk object to map to this device
- **file** – File object to map to this device
- **ctrl_item** – Controller object to serve as parent
- **disk_item** – Existing disk device to update instead of making a new device.

Returns New or updated disk device object.

add_file (*file_path*, *file_id*, *file=None*, *disk=None*)

Add a new file object to the VM or overwrite the provided one.

Parameters

- **file_path** (*str*) – Path to file to add
- **file_id** (*str*) – Identifier string for the file in the VM
- **file** – Existing file object to overwrite
- **disk** – Existing disk object referencing *file*.

Returns New or updated file object

check_sanity_of_disk_device (*disk*, *file*, *disk_item*, *ctrl_item*)

Check if the given disk is linked properly to the other objects.

Parameters

- **disk** – Disk object to validate
- **file** – File object which this disk should be linked to (optional)
- **disk_item** – Disk device object which should link to this disk (optional)
- **ctrl_item** – Controller device object which should link to the *disk_item*

Raises

- **ValueMismatchError** – if the given items are not linked properly.
- **ValueUnsupportedError** – if the *disk_item* has a `HostResource` value in an unrecognized or invalid format.

config_file_to_properties (*file*)

Import each line of a text file into a configuration property.

Raises NotImplementedError if the platform for this OVF does not define `LITERAL_CLI_STRING`

Parameters *file* (*str*) – File name to import.

convert_disk_if_needed (*file_path*, *kind*)

Convert the disk to a more appropriate format if needed.

- All hard disk files are converted to stream-optimized VMDK as it is the only format that VMware supports in OVA packages.
- CD-ROM iso images are accepted without change.

Parameters

- **file_path** (*str*) – Image to inspect and possibly convert
- **kind** (*str*) – Image type (harddisk/cdrom)

Returns

- `file_path`, if no conversion was required
- or a file path in `output_dir` containing the converted image

create_configuration_profile (*id*, *label*, *description*)

Create or update a configuration profile with the given ID.

Parameters

- **id** – Profile identifier
- **label** (*str*) – Brief descriptive label for the profile
- **description** (*str*) – Verbose description of the profile

create_envelope_section_if_absent (*section_tag*, *info_string*, *attrib*={})

If the OVF doesn't already have the given Section, create it.

Parameters

- **section_tag** (*str*) – XML tag of the desired section.
- **info_string** (*str*) – Info string to set if a new Section is created.
- **attrib** (*dict*) – Attributes to filter by when looking for any existing section.

Returns Section element that was found or created

create_network (*label*, *description*)

Define a new network with the given label and description.

Parameters

- **label** (*str*) – Brief label for the network
- **description** (*str*) – Verbose description of the network

classmethod detect_type_from_name (*filename*)

Check the given filename to see if it looks like a type we support.

For our purposes, the file needs to match ".ov[af]" to appear to be an OVF/OVA file. We also support names like "foo.ovf.20150101" as those have been seen in the wild.

Does not check file contents, as the given filename may not yet exist.

Returns '.ovf' or '.ova'

Raises ValueError if filename doesn't match ovf/ova

device_info_str (*device_item*)

Get a one-line summary of a hardware device.

Parameters **device_item** (*OVFItem*) – Device to summarize

Returns Descriptive string such as "harddisk @ IDE 1:0"

find_device_location (*device*)

Find the controller type and address of a given device object.

Parameters **device** – Hardware device object.

Returns (*type*, *address*), such as ("ide", "1:0").

find_disk_from_file_id (*file_id*)

Find the Disk that uses the given file_id for backing.

Parameters `file_id` (*str*) – File identifier string

Returns Disk element matching the file, or None

find_empty_drive (*type*)

Find a disk device that exists but contains no data.

Parameters `type` (*str*) – Either ‘cdrom’ or ‘harddisk’

Returns Hardware device object, or None.

find_item_from_disk (*disk*)

Find the disk Item that references the given Disk.

Parameters `disk` (*xml.etree.ElementTree.Element*) – Disk element

Returns `OVFItem` instance, or None

find_item_from_file (*file*)

Find the disk Item that references the given File.

Parameters `file` (*xml.etree.ElementTree.Element*) – File element

Returns `OVFItem` instance, or None.

find_open_controller (*type*)

Find the first open slot on a controller of the given type.

Parameters `type` (*str*) – ‘ide’ or ‘scsi’

Returns (`ctrl_item`, `address_string`) or (None, None)

find_parent_from_item (*item*)

Find the parent Item of the given Item.

Parameters `item` (*OVFItem*) – Item whose parent is desired

Returns `OVFItem` representing the parent device, or None

generate_manifest (*ovf_file*)

Construct the manifest file for this package, if possible.

Parameters `ovf_file` (*str*) – OVF descriptor file path

Returns True if the manifest was successfully generated, False if not successful (such as if checksum helper tools are unavailable).

get_capacity_from_disk (*disk*)

Get the capacity of the given Disk in bytes.

Parameters `disk` (*xml.etree.ElementTree.Element*) – Disk element

Return type int

get_common_subtype (*type*)

Get the sub-type common to all devices of the given type.

Parameters `type` (*str*) – Device type such as ‘ide’ or ‘memory’.

Returns None, if multiple such devices exist and they do not all have the same sub-type.

Returns Subtype string common to all devices of the type.

get_configuration_profile_ids ()

Get the list of supported configuration profile identifiers.

If this OVF has no defined profiles, returns an empty list. If there is a default profile, it will be first in the list.

get_default_profile_name()

Get the name of the default configuration profile.

Returns Profile name or `None` if none are defined.

get_file_ref_from_disk(disk)

Get the file reference from the given opaque disk object.

Parameters **disk** (*xml.etree.ElementTree.Element*) – ‘Disk’ element

Returns ‘fileRef’ attribute value of this element

get_id_from_file(file)

Get the file ID from the given opaque file object.

Parameters **file** (*xml.etree.ElementTree.Element*) – ‘File’ element

Returns ‘id’ attribute value of this element

get_network_list()

Get the list of network names currently defined in this VM.

Return type list[str]

get_nic_count(profile_list)

Get the number of NICs under the given profile(s).

Parameters **profile_list** (*list*) – Profile(s) of interest.

Return type dict

Returns { profile_name : nic_count }

get_path_from_file(file)

Get the file path from the given opaque file object.

Parameters **file** (*xml.etree.ElementTree.Element*) – ‘File’ element

Returns ‘href’ attribute value of this element

get_platform()

Determine the platform type from the OVF descriptor.

Returns Class object - `GenericPlatform` or a more-specific subclass if recognized as such.

get_property_array()

Get an array of configuration properties.

Returns Array of dicts (one per property) with the keys "key", "value", "qualifiers", "type", "label", and "description".

get_property_value(key)

Get the value of the given property.

Parameters **key** (*str*) – Property identifier

Returns Value of this property, or `None`

get_serial_count(profile_list)

Get the number of serial ports under the given profile(s).

Return type dict

Returns { profile_name : serial_count }

get_subtype_from_device(device)

Get the sub-type of the given opaque device object.

Parameters `device` – Device object to query

Returns `None`, or string such as ‘virtio’ or ‘lsilogic’

get_type_from_device (*device*)

Get the type of the given device.

Parameters `device` (*OVFItem*) – Device object to query

Returns string such as ‘ide’ or ‘memory’

info_string (*TEXT_WIDTH=79, verbosity_option=None*)

Get a descriptive string summarizing the contents of this OVF.

Parameters

- **TEXT_WIDTH** (*int*) – Line length to wrap to where possible.
- **verbosity_option** (*str*) – ‘brief’, `None` (default), or ‘verbose’

Returns Wrapped, appropriately verbose string.

profile_info_string (*TEXT_WIDTH=79, verbosity_option=None, enumerate=False*)

Get a string summarizing available configuration profiles.

Parameters

- **TEXT_WIDTH** (*int*) – Line length to wrap to if possible
- **verbosity_option** (*str*) – ‘brief’, `None` (default), or ‘verbose’
- **enumerate** (*boolean*) – If `True`, number the profiles.

Returns Appropriately formatted and verbose string.

search_from_controller (*controller, address*)

From the controller type and device address, look for existing disk.

This implementation uses the parameters to find matching controller and disk `Item` elements, then using the disk `Item` to find matching `File` and/or `Disk`.

Parameters

- **controller** (*str*) – ‘ide’ or ‘scsi’
- **address** (*str*) – Device address such as ‘1:0’

Returns (*file, disk, ctrl_item, disk_item*), any or all of which may be `None`

search_from_file_id (*file_id*)

From the given file ID, try to find any existing objects.

This implementation uses the given *file_id* to find a matching `File` in the OVF, then using that to find a matching `Disk` and `Item` entries.

Parameters `file_id` (*str*) – Filename to search from

Returns (*file, disk, ctrl_item, disk_item*), any or all of which may be `None`

search_from_filename (*filename*)

From the given filename, try to find any existing objects.

This implementation uses the given *filename* to find a matching `File` in the OVF, then using that to find a matching `Disk` and `Item` entries.

Parameters `filename` (*str*) – Filename to search from

Returns (*file, disk, ctrl_item, disk_item*), any or all of which may be `None`

set_capacity_of_disk (*disk, capacity_bytes*)

Set the storage capacity of the given Disk.

Tries to use the most human-readable form possible (i.e., 8 GB instead of 8589934592 bytes).

Parameters

- **disk** (*xml.etree.ElementTree.Element*) – Disk to update
- **capacity_bytes** (*int*) – Disk capacity, in bytes

set_cpu_count (*cpus, profile_list*)

Set the number of CPUs.

Parameters

- **cpus** (*int*) – Number of CPUs
- **profile_list** (*list*) – Change only the given profiles

set_ide_subtype (*type, profile_list*)

Set the device subtype for the IDE controller(s).

Parameters

- **type** (*str*) – IDE subtype string
- **profile_list** (*list*) – Change only the given profiles

set_long_version (*version_string*)

Set the FullVersion element's value.

Parameters **version_string** (*str*) – Long descriptive version string.

set_memory (*megabytes, profile_list*)

Set the amount of RAM, in megabytes.

Parameters

- **megabytes** (*int*) – Memory value, in megabytes
- **profile_list** (*list*) – Change only the given profiles

set_nic_count (*count, profile_list*)

Set the given profile(s) to have the given number of NICs.

Parameters

- **count** (*int*) – number of NICs
- **profile_list** (*list*) – Change only the given profiles

set_nic_mac_addresses (*mac_list, profile_list*)

Set the MAC addresses for NICs under the given profile(s).

Note: If the length of `mac_list` is less than the number of NICs, will use the last entry in the list for all remaining NICs.

Parameters

- **mac_list** (*list*) – List of MAC addresses to assign to NICs
- **profile_list** (*list*) – Change only the given profiles

set_nic_names (*name_list*, *profile_list*)

Set the device names for NICs under the given profile(s).

TODO: document magic expansion syntax here

Parameters

- **name_list** (*list*) – List of names to assign.
- **profile_list** (*list*) – Change only the given profiles

set_nic_networks (*network_list*, *profile_list*)

Set the NIC to network mapping for NICs under the given profile(s).

Note: If the length of *network_list* is less than the number of NICs, will use the last entry in the list for all remaining NICs.

Parameters

- **network_list** (*list*) – List of networks to map NICs to
- **profile_list** (*list*) – Change only the given profiles

set_nic_type (*type*, *profile_list*)

Set the hardware type for NICs.

Parameters

- **type** (*str*) – NIC hardware type
- **profile_list** (*list*) – Change only the given profiles.

set_output_file (*output_file*)

Validate the given output filename and save it for later use.

Parameters **output_file** (*str*) – Output filename

Raises **ValueUnsupportedError** if `detect_type_from_name()` fails

set_property_value (*key*, *value*)

Set the value of the given property (converting value if needed).

Parameters

- **key** (*str*) – Property identifier
- **value** – Value to set for this property

Returns the (converted) value that was set.

set_scsi_subtype (*type*, *profile_list*)

Set the device subtype for the SCSI controller(s).

Parameters

- **type** (*str*) – SCSI subtype string
- **profile_list** (*list*) – Change only the given profiles

set_serial_connectivity (*conn_list*, *profile_list*)

Set the serial port connectivity under the given profile(s).

Parameters

- **conn_list** (*list*) – List of connectivity strings

- **profile_list** (*list*) – Change only the given profiles

set_serial_count (*count*, *profile_list*)

Set the given profile(s) to have the given number of serial ports.

Parameters

- **count** (*int*) – Number of serial ports
- **profile_list** (*list*) – Change only the given profiles

set_short_version (*version_string*)

Set the Version element's value.

Parameters **version_string** (*str*) – Short descriptive version string.

set_system_type (*type_list*)

Set the virtual system type(s) supported by this virtual machine.

For an OVF, this corresponds to the VirtualSystemType element.

Parameters **type_list** (*list*) – List of system type strings

tar (*ovf_descriptor*, *tar_file*)

Create a .ova tar file based on the given OVF descriptor.

Parameters

- **ovf_descriptor** (*str*) – File path for an OVF descriptor
- **tar_file** (*str*) – File path for the desired OVA archive.

untar (*file*)

Untar the provided .ova to a the working directory.

Parameters **file** (*str*) – OVA file path

Raises **VMInitError** if the given file does not represent a valid OVA archive.

Returns Path to extracted OVF descriptor

write ()

Write OVF or OVA to output_file, if set.

class **OVFNameHelper** (*version*)

Bases: object

Helper class for OVF.

Provides string constants for easier lookup of various OVF XML elements and attributes.

class **OVFHardware** (*ovf*)

Helper class for OVF.

Represents all hardware items defined by this OVF; i.e., the contents of all Items in the VirtualHardwareSection.

Fundamentally it's just a dict of [OVFItem](#) objects with a bunch of helper methods.

clone_item (*parent_item*, *profile_list*)

Clone an [OVFItem](#) to create a new instance.

Parameters

- **parent_item** (*OVFItem*) – Instance to clone from
- **profile_list** (*list*) – List of profiles to clone into

Returns (*instance*, *ovfitem*)

find_all_items (*resource_type=None, properties=None, profile_list=None*)

Find all items matching the given type, properties, and profiles.

Parameters

- **resource_type** –
- **value]** **properties** (*dict[property,)* – Property values to match
- **profile_list** (*list*) – List of profiles to filter on

Returns list of `OVFItem` instances

find_item (*resource_type=None, properties=None, profile=None*)

Find the only `OVFItem` of the given `resource_type`.

Parameters

- **resource_type** –
- **properties** –
- **profile** – Single profile ID to search within

Return type `OVFItem` or `None`

Raises `LookupError` if more than one such Item exists.

find_unused_instance_id ()

Find the first available `InstanceID` number.

Return type string

get_item_count (*resource_type, profile*)

Wrapper for `get_item_count_per_profile()`.

Parameters

- **resource_type** (*str*) –
- **profile** (*str*) – Single profile identifier string to look up.

Returns Number of items of this type in this profile.

get_item_count_per_profile (*resource_type, profile_list*)

Get the number of Items of the given type per profile.

Items present under “no profile” will be counted against the total for each profile.

Parameters

- **resource_type** (*str*) –
- **profile_list** (*list*) – List of profiles to filter on (default: apply across all profiles)

Return type `dict[profile, count]`

new_item (*resource_type, profile_list=None*)

Create a new `OVFItem` of the given type.

Parameters

- **resource_type** (*str*) –
- **profile_list** (*list*) – Profiles the new item should belong to

Returns (`instance, ovfitem`)

set_item_count_per_profile (*resource_type*, *count*, *profile_list*)

Set the number of items of a given type under the given profile(s).

If the new count is greater than the current count under this profile, then additional instances that already exist under another profile will be added to this profile, starting with the lowest-sequence instance not already present, and only as a last resort will new instances be created.

If the new count is less than the current count under this profile, then the highest-numbered instances will be removed preferentially.

Parameters

- **resource_type** (*str*) – ‘cpu’, ‘harddisk’, etc.
- **count** (*int*) – Desired number of items
- **profile_list** (*list*) – List of profiles to filter on (default: apply across all profiles)

set_item_values_per_profile (*resource_type*, *property*, *value_list*, *profile_list*, *default=None*)

Set value(s) for a property of multiple items of a type.

Parameters

- **resource_type** (*str*) – Device type such as ‘harddisk’ or ‘cpu’
- **property** (*str*) – Property name to update
- **value_list** (*list*) – List of values to set (one value per item of the given *resource_type*)
- **profile_list** (*list*) – List of profiles to filter on (default: apply across all profiles)
- **default** – If there are more matching items than entries in *value_list*, set extra items to this value

set_value_for_all_items (*resource_type*, *property*, *new_value*, *profile_list*, *create_new=False*)

Set a property to the given value for all items of the given type.

If no items of the given type exist, will create a new `Item` if *create_new* is set to `True`; otherwise will log a warning and do nothing.

Parameters

- **resource_type** (*str*) – Resource type such as ‘cpu’ or ‘harddisk’
- **property** (*str*) – Property name to update
- **new_value** – New value to set the property to
- **profile_list** (*list*) – List of profiles to filter on (default: apply across all profiles)
- **create_new** (*boolean*) – Whether to create a new entry if no items of this *resource_type* presently exist.

update_xml ()

Regenerate all `Items` under the `VirtualHardwareSection`, if needed.

Will do nothing if no `Items` have been changed.

class OVHardwareDataError

Bases: `exceptions.Exception`

The input data used to construct an `OVHardware` is not sane.

class OVItem (*ovf*, *item=None*)

Helper class for `OVF`.

Represents all variations of a given hardware `Item` amongst different hardware configuration profiles.

In essence, it is:

- a dict of `Item` properties (indexed by element name)
- each of which is a dict of sets of profiles (indexed by element value)

add_item (*item*)

Add the given `Item` element to this `OVFItem`.

Parameters `item` – XML `Item` element

Raises `OVFItemDataError` if the new `Item` conflicts with existing data already in the `OVFItem`.

add_profile (*new_profile*, *from_item=None*)

Add a new profile to this item.

Parameters

- **new_profile** (*str*) – Profile name to add
- **from_item** (`OVFItem`) – Item to inherit properties from. If unset, this defaults to `self`.

generate_items ()

Get a list of `Item` XML elements derived from this object's data.

Return type `list[xml.etree.ElementTree.Element]`

get (*tag*)

Get the dict associated with the given XML tag, if any.

Parameters `tag` (*str*) – XML tag to look up

Return type `dict`

Returns Dictionary of values associated with this tag (TODO?)

get_all_values (*tag*)

Get the set of all value strings for the given tag.

Parameters `tag` –

Return type `set`

get_value (*tag*, *profiles=None*)

Get the value for the given tag under the given profiles.

If the tag does not exist under these profiles, or the tag values differ across the profiles, returns `None`.

Parameters

- **tag** (*str*) – Tag that the value is associated with
- **profiles** – set of profile names, or `None`

Returns Value string or `None`

has_profile (*profile*)

Check if this `Item` exists under the given profile.

Parameters `profile` (*str*) – Profile name

Return type `boolean`

remove_profile (*profile*)

Remove all trace of the given profile from this item.

Parameters `profile` – Profile name to remove

set_property (*key*, *value*, *profiles=None*, *overwrite=True*)

Store the value and profiles associated with it for the given key.

Parameters

- **key** (*str*) – Property key
- **value** – Value associated with *key*
- **profiles** (*list[str]*) – If `None`, set for all profiles currently known to this item, else set only for the given list of profiles.
- **overwrite** (*boolean*) – Whether to permit overwriting of existing value set in this item.

Raises OVFIItemDataError if a value is already defined and would be overwritten, unless `overwrite` is `True`

validate ()

Verify that the OVFIItem describes a valid set of items.

Raises RuntimeError if validation fails and self-repair is impossible.

ATTRIB_KEY_SUFFIX = ‘{Item attribute}’

ELEMENT_KEY_SUFFIX = ‘{custom element}’

class OVFIItemDataError

Bases: `exceptions.Exception`

Data to be added to an `OVFIItem` conflicts with existing data.

6.2 Command modules

<code>COT.submodule</code>	Parent classes for implementing COT subcommands.
<code>COT.add_disk</code>	Module for adding disks to VMs.
<code>COT.add_file</code>	Module for adding files to VM definitions.
<code>COT.deploy</code>	Module for deploying VM descriptions to a hypervisor to instantiate VMs.
<code>COT.edit_hardware</code>	Module for editing hardware details of a VM.
<code>COT.edit_product</code>	Module for editing product information in a VM description.
<code>COT.edit_properties</code>	Module for managing VM environment configuration properties.
<code>COT.help</code>	Provide ‘help’ keyword for COT CLI.
<code>COT.info</code>	Implements “info” subcommand.
<code>COT.inject_config</code>	Implements “inject-config” command.

6.2.1 COT.submodule module

Parent classes for implementing COT subcommands.

Classes

<code>COTGenericSubmodule</code>	Abstract interface for COT command submodules.
<code>COTReadOnlySubmodule</code>	Class for submodules that do not modify the OVF, such as ‘deploy’.
<code>COTSubmodule</code>	Class for submodules that read and write the OVF.

class COTGenericSubmodule (*UI*)

Bases: `object`

Abstract interface for COT command submodules.

Attributes: `vm`, `UI`

Note: Generally a command should not inherit directly from this class, but should instead subclass `COTReadOnlySubmodule` or `COTSubmodule` as appropriate.

create_subparser (*parent*)

Add subparser for the CLI of this submodule.

Parameters `parent` (*object*) – Subparser grouping object returned by `ArgumentParser.add_subparsers()`

Returns (`label`, `subparser`) or (`"", None`) if this module has no CLI

destroy ()

Destroy any VM associated with this submodule.

finished ()

Do any final actions before being destroyed.

This class does nothing; subclasses may choose to do things like write their VM state out to a file.

ready_to_run ()

Check whether the module is ready to `run()`.

Returns (`True`, `ready_message`) or (`False`, `reason_why_not`)

run ()

Do the actual work of this submodule.

Raises `InvalidInputError` if `ready_to_run()` reports `False`

UI = None

User interface instance (`UI` or subclass) to use.

vm = None

Virtual machine description (`VMDescription`).

class COTReadOnlySubmodule (*UI*)

Bases: `COT.submodule.COTGenericSubmodule`

Class for submodules that do not modify the OVF, such as ‘deploy’.

Inherited attributes: `vm`, `UI`

Attributes: `package`

ready_to_run ()

Check whether the module is ready to `run()`.

Returns (`True`, `ready_message`) or (`False`, `reason_why_not`)

package

VM description file to read from.

Calls `COT.vm_factory.VMFactory.create()` to instantiate `self.vm` from the provided file.

Raises `InvalidInputError` if the file does not exist.

class COTSubmodule (*UI*)

Bases: `COT.submodule.COTGenericSubmodule`

Class for submodules that read and write the OVF.

Inherited attributes: `vm`, `UI`

Attributes: `package`, `output`

finished()

Write the current VM state out to disk if requested.

ready_to_run()

Check whether the module is ready to `run()`.

Returns `(True, ready_message)` or `(False, reason_why_not)`

run()

Do the actual work of this submodule.

If `output` was not previously set, automatically sets it to the value of `PACKAGE`.

Raises `InvalidInputError` if `ready_to_run()` reports `False`

output

Output file for this submodule.

If the specified file already exists, will prompt the user (`confirm_or_die()`) to confirm overwriting the existing file.

package

VM description file to read (and possibly write).

Calls `COT.vm_factory.VMFactory.create()` to instantiate `self.vm` from the provided file.

Raises `InvalidInputError` if the file does not exist.

6.2.2 COT.add_disk module

Module for adding disks to VMs.

<code>COTAddDisk(UI)</code>	Add or replace a disk in a virtual machine.
<code>add_disk_worker(vm, UI, DISK_IMAGE[, type, ...])</code>	Worker function for actually adding the disk.

class COTAddDisk (UI)

Bases: `COT.submodule.COTSubmodule`

Add or replace a disk in a virtual machine.

Inherited attributes: `UI`, `package`, `output`

Attributes: `disk_image`, `type`, `file_id`, `controller`, `subtype`, `address`, `diskname`, `description`

create_subparser (parent)

Add subparser for the CLI of this submodule.

Parameters **parent** (*object*) – Subparser grouping object returned by `ArgumentParser.add_subparsers()`

Returns `('add-disk', subparser)`

ready_to_run()

Check whether the module is ready to `run()`.

Returns `(True, ready_message)` or `(False, reason_why_not)`

run()

Do the actual work of this submodule.

Raises `InvalidInputError` if `ready_to_run()` reports `False`

`validate_controller_address` (*controller*, *address*)

Check validity of the given address string for the given controller.

Helper method for the `controller/address` setters.

Parameters

- **`controller`** (*str*) – ‘ide’ or ‘scsi’
- **`address`** (*str*) – A string like ‘0:0’ or ‘2:10’

Raises `InvalidInputError` if the address/controller combo is invalid.

`address`

Disk device address on controller (1:0, etc.).

Raises `InvalidInputError`, see `validate_controller_address()`

`controller`

Disk controller type (ide, scsi).

Raises `InvalidInputError`, see `validate_controller_address()`

`description = None`

Description of the disk.

`disk_image`

Path to disk image file to add to the VM.

Raises `InvalidInputError` if the file does not exist.

`diskname = None`

Name string for the disk.

`file_id = None`

File identifier to map disk to file.

`subtype = None`

Controller subtype, such as “virtio”.

`type = None`

Disk type (‘harddisk’ or ‘cdrom’).

`add_disk_worker` (*vm*, *UI*, *DISK_IMAGE*, *type=None*, *file_id=None*, *controller=None*, *subtype=None*, *address=None*, *diskname=None*, *description=None*)

Worker function for actually adding the disk.

All parameters except `vm`, `UI`, and `DISK_IMAGE` are optional and will be automatically determined by COT if unspecified.

Parameters

- **`vm`** (`OVF` or other `VMDescription` subclass) – The virtual machine being edited.
- **`UI`** (instance of `UI` or subclass.) – User interface in effect.
- **`DISK_IMAGE`** (*str*) – path to disk image to add to the VM.
- **`type`** (*str*) – Disk type: ‘cdrom’ or ‘harddisk’. If not specified, will be derived automatically from the `DISK_IMAGE` file name extension.
- **`file_id`** (*str*) – Identifier of the disk file in the VM. If not specified, the VM will automatically derive an appropriate value.

- **controller** (*str*) – Disk controller type: 'ide' or 'scsi'. If not specified, will be derived from the *type* and the *platform* of the given *vm*.
- **subtype** (*str*) – Controller subtype ('virtio', 'lsilogic', etc.)
- **address** (*str*) – Disk device address on its controller (such as '1:0'). If this matches an existing disk device, that device will be overwritten. If not specified, the first available address not already occupied by an existing device will be selected.
- **diskname** (*str*) – Name for disk device
- **description** (*str*) – Description of disk device

6.2.3 COT.add_file module

Module for adding files to VM definitions.

COTAddFile(UI)	Add a file (such as a README) to the package.
----------------	---

class COTAddFile (*UI*)

Bases: `COT.submodule.COTSubmodule`

Add a file (such as a README) to the package.

Inherited attributes: `UI`, `package`, `output`

Attributes: `file`, `file_id`

create_subparser (*parent*)

Add subparser for the CLI of this submodule.

Parameters *parent* (*object*) – Subparser grouping object returned by `ArgumentParser.add_subparsers()`

Returns ('add-file', subparser)

ready_to_run ()

Check whether the module is ready to `run()`.

Returns (True, ready_message) or (False, reason_why_not)

run ()

Do the actual work of this submodule.

Raises `InvalidInputError` if `ready_to_run()` reports False

file

File to be added to the package.

Raises `InvalidInputError` if the file does not exist.

file_id = None

File identifier string.

6.2.4 COT.deploy module

Module for deploying VM descriptions to a hypervisor to instantiate VMs.

Classes

<code>COTDeploy</code>	Semi-abstract class for submodules used to deploy a VM to a hypervisor.
<code>COTDeployESXi</code>	Submodule for deploying VMs on ESXi and VMware vCenter/vSphere.

class `COTDeploy` (*UI*)

Bases: `COT.submodule.COTReadOnlySubmodule`

Semi-abstract class for submodules used to deploy a VM to a hypervisor.

Provides some baseline parameters and input validation that are expected to be common across all concrete subclasses.

Inherited attributes: `UI`, `package`,

Attributes: `generic_parser`, `parser`, `subparsers`, `hypervisor`, `configuration`, `username`, `password`, `power_on`, `vm_name`, `network_map`

create_subparser (*parent*)

Add subparser for the CLI of this submodule.

Note: Unlike most submodules, this one has subparsers of its own - `'cot deploy PACKAGE <hypervisor>'` so subclasses of this module should call `super().create_subparser(parent)` (to create the main 'deploy' subparser) then call `self.subparsers.add_parser()` to add their own sub-subparser.

Parameters *parent* (*object*) – Subparser grouping object returned by `ArgumentParser.add_subparsers()`

Returns ('deploy', subparser)

ready_to_run ()

Check whether the module is ready to run ().

Returns (True, ready_message) or (False, reason_why_not)

configuration

VM configuration profile to use for deployment.

Raise `InvalidInputError` if not a profile defined in the VM.

generic_parser = None

Generic parser object providing args that most subclasses will use.

Subclasses can call `self.subparsers.add_parser(parents=[self.generic_parser])` to automatically inherit this set of args

hypervisor

Hypervisor to deploy to.

Raise `InvalidInputError` if not a recognized value.

network_map = None

Mapping of network names to networks

parser = None

Subparser providing `cot deploy PACKAGE ... CLI`.

password = None

Server login password.

power_on

Whether to automatically power on the VM after deployment.

subparsers = None

Subparser grouping for hypervisor-specific sub-subparsers.

Subclasses should generally have their `create_subparser()` implementations create their sub-subparsers under `subparsers` and NOT under `parent`.

username = None

Server login username.

vm_name = None

Name of the created virtual machine

class COTDeployESXi (UI)

Bases: `COT.deploy.COTDeploy`

Submodule for deploying VMs on ESXi and VMware vCenter/vSphere.

Inherited attributes: `UI`, `package`, `generic_parser`, `parser`, `subparsers`, `hypervisor`, `configuration`, `username`, `password`, `power_on`, `vm_name`, `network_map`

Attributes: `locator`, `datastore`, `ovftool_args`

create_subparser (parent)

Add subparser for the CLI of this submodule.

This will create the shared `parser` under `parent`, then create our own sub-subparser under `subparsers`.

Parameters `parent` (*object*) – Subparser grouping object returned by `ArgumentParser.add_subparsers()`

Returns ('deploy', subparser)

ready_to_run ()

Check whether the module is ready to `run()`.

Returns (True, ready_message) or (False, reason_why_not)

run ()

Do the actual work of this submodule - deploying to ESXi.

Raises `InvalidInputError` if `ready_to_run()` reports False

datastore = None

ESXi datastore to deploy to.

locator = None

vSphere target locator.

ovftool_args

List of CLI arguments to pass through to `ovftool`.

6.2.5 COT.edit_hardware module

Module for editing hardware details of a VM.

Classes

<code>COTEditHardware</code>	Edit hardware information (CPUs, RAM, NICs, etc.).
------------------------------	--

class **COTEditHardware** (*UI*)

Bases: `COT.submodule.COTSubmodule`

Edit hardware information (CPUs, RAM, NICs, etc.).

Inherited attributes: `UI`, `package`, `output`

Attributes: `profiles`, `cpus`, `memory`, `nics`, `nic_type`, `mac_addresses_list`, `nic_networks`, `nic_names`, `serial_ports`, `serial_connectivity`, `scsi_subtype`, `ide_subtype`, `virtual_system_type`

create_subparser (*parent*)

Add subparser for the CLI of this submodule.

Parameters **parent** (*object*) – Subparser grouping object returned by `ArgumentParser.add_subparsers()`

Returns ('edit-hardware', subparser)

ready_to_run ()

Check whether the module is ready to `run()`.

Returns (True, ready_message) or (False, reason_why_not)

run ()

Do the actual work of this submodule.

Raises **InvalidInputError** if `ready_to_run()` reports False

cpus

Number of CPUs to set.

ide_subtype = None

Subtype string for IDE controllers

mac_addresses_list = None

List of MAC addresses to set.

memory

Amount of RAM (in megabytes) to set.

nic_names = None

List of NIC name strings

nic_networks = None

List of NIC-to-network mappings.

nic_type

NIC type string to set.

nics

Number of NICs to set.

profiles = None

Configuration profile(s) to edit.

scsi_subtype = None

Subtype string for SCSI controllers

serial_connectivity = None

List of serial connection strings.

serial_ports

Serial port count to set.

virtual_system_type = None
Virtual system type

6.2.6 COT.edit_product module

Module for editing product information in a VM description.

Classes

<code>COTEditProduct</code>	Edit product information (short version, long version).
-----------------------------	---

```
class COTEditProduct (UI)
    Bases: COT.submodule.COTSubmodule

    Edit product information (short version, long version).

    Inherited attributes: UI, package, output
    Attributes: version, full_version

    create_subparser (parent)
        Add subparser for the CLI of this submodule.

        Parameters parent (object) – Subparser grouping object returned by
            ArgumentParser.add_subparsers()

        Returns ('edit-product', subparser)

    ready_to_run ()
        Check whether the module is ready to run().

        Returns (True, ready_message) or (False, reason_why_not)

    run ()
        Do the actual work of this submodule.

        Raises InvalidInputError if ready_to_run() reports False

    full_version = None
        Long version string.

    version = None
        Short version string.
```

6.2.7 COT.edit_properties module

Module for managing VM environment configuration properties.

Classes

<code>COTEditProperties</code>	Edit OVF environment XML properties.
--------------------------------	--------------------------------------

```
class COTEditProperties (UI)
    Bases: COT.submodule.COTSubmodule

    Edit OVF environment XML properties.

    Inherited attributes: UI, package, output
    Attributes: config_file, properties
```

create_subparser (*parent*)

Add subparser for the CLI of this submodule.

Parameters **parent** (*object*) – Subparser grouping object returned by `ArgumentParser.add_subparsers()`

Returns ('edit-properties', subparser)

edit_properties_interactive (*vm*)

Present an interactive UI for the user to edit properties.

Parameters **vm** – TODO shouldn't be necessary - use self.vm?

run ()

Do the actual work of this submodule.

Raises **InvalidInputError** if `ready_to_run()` reports False

config_file

Path to plaintext file to read configuration lines from.

Raise `InvalidInputError` if the file does not exist.

properties

List of property (key, value) tuples to update.

6.2.8 COT.help module

Provide 'help' keyword for COT CLI.

class COTHelp (*UI*)

Bases: `COT.submodule.COTGenericSubmodule`

Provide 'help <subcommand>' syntax.

Inherited attributes: `UI`

Attributes: `subcommand`

create_subparser (*parent*)

Add subparser for the CLI of this submodule.

Parameters **parent** (*object*) – Subparser grouping object returned by `ArgumentParser.add_subparsers()`

Returns ('help', subparser)

run ()

Display the help menu for the specified subcommand.

subcommand

CLI subcommand to give help for.

If None, then help will be displayed for the COT global parser.

6.2.9 COT.info module

Implements "info" subcommand.

class COTInfo (*UI*)

Bases: `COT.submodule.COTGenericSubmodule`

Display VM information string.

Inherited attributes: UI

Attributes: `package_list`, `verbosity`

create_subparser (*parent*)

Add subparser for the CLI of this submodule.

Parameters **parent** (*object*) – Subparser grouping object returned by `ArgumentParser.add_subparsers()`

Returns ('info', subparser)

ready_to_run ()

Check whether the module is ready to `run()`.

Returns (True, ready_message) or (False, reason_why_not)

run ()

Do the actual work of this submodule.

Raises `InvalidInputError` if `ready_to_run()` reports False

package_list

List of VM definitions to get information for.

verbosity

Verbosity of information displayed.

6.2.10 COT.inject_config module

Implements “inject-config” command.

class `COTInjectConfig` (*UI*)

Bases: `COT.submodule.COTSubmodule`

Wrap configuration file(s) into a disk image embedded into the VM.

Inherited attributes: UI, package, output

Attributes: `config_file`, `secondary_config_file`

create_subparser (*parent*)

Add subparser for the CLI of this submodule.

Parameters **parent** (*object*) – Subparser grouping object returned by `ArgumentParser.add_subparsers()`

Returns ('inject-config', subparser)

ready_to_run ()

Check whether the module is ready to `run()`.

Returns (True, ready_message) or (False, reason_why_not)

run ()

Do the actual work of this submodule.

Raises `InvalidInputError` if `ready_to_run()` reports False

config_file

Primary configuration file.

Raises

- `InvalidInputError` – if the file does not exist

- **InvalidInputError** – if the *platform described by :attr: 'package'* doesn't support configuration files.

secondary_config_file

Secondary configuration file.

Raises

- **InvalidInputError** – if the file does not exist
- **InvalidInputError** – if the platform described by `package` doesn't support secondary configuration files.

6.3 Helper library modules

<code>COT.data_validation</code>	Various helpers for data sanity checks.
<code>COT.helper_tools</code>	Third-party helper tools.
<code>COT.platforms</code>	Handles behavior that varies between guest platforms.

6.3.1 COT.data_validation module

Various helpers for data sanity checks.

Exceptions

<code>InvalidInputError</code>	Miscellaneous error during validation of user input.
<code>ValueMismatchError</code>	Values which were expected to be equal turned out to be not equal.
<code>ValueUnsupportedError</code>	An unsupported value was provided.
<code>ValueTooLowError</code>	A numerical input was less than the lowest supported value.
<code>ValueTooHighError</code>	A numerical input was higher than the highest supported value.

Functions

<code>check_for_conflict</code>	Make sure the list does not contain references to more than one object.
<code>device_address</code>	Parser helper function for device address arguments.
<code>mac_address</code>	Parser helper function for MAC address arguments.
<code>match_or_die</code>	Make sure “first” and “second” are equal or raise an error.
<code>natural_sort</code>	Sort the given list “naturally” rather than in ASCII order.
<code>no_whitespace</code>	Parser helper function for arguments not allowed to contain whitespace.
<code>non_negative_int</code>	Parser helper function for integer arguments that must be 0 or more.
<code>positive_int</code>	Parser helper function for integer arguments that must be 1 or more.
<code>to_string</code>	Get string representation of an object, special-case for XML Element.
<code>validate_int</code>	Parser helper function for validating integer arguments in a range.

exception InvalidInputError

Bases: `exceptions.ValueError`

Miscellaneous error during validation of user input.

exception ValueMismatchError

Bases: `exceptions.ValueError`

Values which were expected to be equal turned out to be not equal.

exception ValueTooHighError (*value_type, actual, expected*)

Bases: `COT.data_validation.ValueUnsupportedError`

A numerical input was higher than the highest supported value.

Variables

- **value_type** – descriptive string
- **actual_value** – invalid value that was provided
- **expected_value** – maximum supported value

exception ValueTooLowError (*value_type, actual, expected*)

Bases: `COT.data_validation.ValueUnsupportedError`

A numerical input was less than the lowest supported value.

Variables

- **value_type** – descriptive string
- **actual_value** – invalid value that was provided
- **expected_value** – minimum supported value

exception ValueUnsupportedError (*value_type, actual, expected*)

Bases: `COT.data_validation.InvalidInputError`

An unsupported value was provided.

Variables

- **value_type** – descriptive string
- **actual_value** – invalid value that was provided
- **expected_value** – expected (valid) value or values (item or list)

check_for_conflict (*label, li*)

Make sure the list does not contain references to more than one object.

Parameters

- **label** (*str*) – Descriptive label to be used if an error is raised
- **li** (*list*) – List of object references (which may include None)

Raises ValueMismatchError if references differ

Returns the object or None

device_address (*string*)

Parser helper function for device address arguments.

Validate string is an appropriately formed device address such as '1:0'.

Parameters **string** (*str*) – String to validate

Raises InvalidInputError if string is not a well-formatted device address

Returns Validated string (with leading/trailing whitespace stripped)

mac_address (*string*)

Parser helper function for MAC address arguments.

Validate whether a string is a valid MAC address. Recognized formats are:

• `XX:XX:XX:XX:XX:XX`

•XX-XX-XX-XX-XX-XX

•XXXX.XXXX.XXXX

Parameters *string* – String to validate

Raises `InvalidInputError` if string is not a valid MAC address

Returns Validated string(with leading/trailing whitespace stripped)

match_or_die (*first_label*, *first*, *second_label*, *second*)

Make sure “first” and “second” are equal or raise an error.

Parameters

- **first_label** (*str*) – Descriptive label for *first*
- **first** – First object to compare
- **second_label** (*str*) – Descriptive label for *second*
- **second** – Second object to compare

Raises `ValueMismatchError` if *first* != *second*

natural_sort (*l*)

Sort the given list “naturally” rather than in ASCII order.

E.g, “10” comes after “9” rather than between “1” and “2”.

See also http://nedbatchelder.com/blog/200712/human_sorting.html

Parameters *l* (*list*) – List to sort

Returns Sorted list

no_whitespace (*string*)

Parser helper function for arguments not allowed to contain whitespace.

Parameters *string* (*str*) – String to validate

Raises `InvalidInputError` if string contains internal whitespace

Returns Validated string (with leading/trailing whitespace stripped)

non_negative_int (*string*)

Parser helper function for integer arguments that must be 0 or more.

Alias for `validate_int()` setting *min* to 0.

positive_int (*string*)

Parser helper function for integer arguments that must be 1 or more.

Alias for `validate_int()` setting *min* to 1.

to_string (*obj*)

Get string representation of an object, special-case for XML Element.

validate_int (*string*, *min=None*, *max=None*, *label='input'*)

Parser helper function for validating integer arguments in a range.

Parameters

- **string** (*str*) – String to convert to an integer and validate
- **min** (*int*) – Minimum valid value (optional)
- **max** (*int*) – Maximum valid value (optional)

- **label** (*str*) – Label to include in any errors raised

Returns Validated integer value

Raises

- **ValueUnsupportedError** – if `string` can't be converted to `int`
- **ValueTooLowError** – if value is less than `min`
- **ValueTooHighError** – if value is more than `max`

6.3.2 COT.helper_tools module

Third-party helper tools.

Abstracts away operations that require third-party helper programs, especially those that are not available through PyPI.

Exceptions

<code>HelperNotFoundError</code>	A helper program cannot be located.
<code>HelperError</code>	A helper program exited with non-zero return code.

Functions

<code>check_call</code>	Wrapper for <code>subprocess.check_call()</code> .
<code>check_output</code>	Wrapper for <code>subprocess.check_output()</code> .
<code>convert_disk_image</code>	Convert the given disk image to the requested format/subformat.
<code>create_disk_image</code>	Create a new disk image at the requested location.
<code>get_checksum</code>	Get the checksum of the given file.
<code>get_disk_capacity</code>	Get the storage capacity of the given disk image.
<code>get_disk_format</code>	Get the disk image format of the given file.
<code>get_ovftool_version</code>	Get installed ovftool version as a <code>StrictVersion</code> object.
<code>get_qemu_img_version</code>	Get installed qemu-img version as a <code>StrictVersion</code> object.
<code>validate_ovf_for_esxi</code>	Use VMware's ovftool program to validate an OVF or OVA.

exception HelperError

Bases: `exceptions.EnvironmentError`

A helper program exited with non-zero return code.

exception HelperNotFoundError

Bases: `exceptions.OSError`

A helper program cannot be located.

check_call (*args*, *require_success=True*)

Wrapper for `subprocess.check_call()`.

Unlike `check_output()` below, this does not redirect stdout/stderr; all output from the subprocess will be sent to stdout/stderr as normal.

Parameters

- **args** (*list*) – Command to invoke and its associated args
- **require_success** (*boolean*) – If `False`, do not raise an error when the command exits with a return code other than 0

Raises

- **HelperNotFoundError** – if the command doesn't exist (instead of a `OSError`)
- **HelperError** – if the command returns a value other than 0 and `require_success` is not `False`

check_output (*args*, *require_success=True*)

Wrapper for `subprocess.check_output()`.

Automatically redirects `stderr` to `stdout`, captures both to a buffer, and generates a debug message with the `stdout` contents.

Parameters

- **args** (*list*) – Command to invoke and its associated args
- **require_success** (*boolean*) – If `False`, do not raise an error when the command exits with a return code other than 0

Returns Captured `stdout/stderr` from the command

Raises

- **HelperNotFoundError** – if the command doesn't exist (instead of a `OSError`)
- **HelperError** – if the command returns a value other than 0 and `require_success` is not `False`

convert_disk_image (*file_path*, *output_dir*, *new_format*, *new_subformat=None*)

Convert the given disk image to the requested format/subformat.

If the disk is already in this format then it is unchanged; otherwise, will convert to a new disk in the specified `output_dir` and return its path.

Current supported conversions:

- `.vmdk` (any format) to `.vmdk` (`streamOptimized`)
- `.img` to `.vmdk` (`streamOptimized`)

Parameters

- **file_path** (*str*) – Disk image file to inspect/convert
- **output_dir** (*str*) – Directory to place converted image into, if needed
- **new_format** (*str*) – Desired final format
- **new_subformat** (*str*) – Desired final subformat

Returns

- `file_path`, if no conversion was required
- or a file path in `output_dir` containing the converted image

Raises `ValueUnsupportedError` if the `new_format` and/or `new_subformat` are not supported conversion targets.

create_disk_image (*file_path*, *file_format=None*, *capacity=None*, *contents=[]*)

Create a new disk image at the requested location.

Either `capacity` or `contents` or both must be specified.

Parameters

- **file_path** (*str*) – Desired location of new disk image
- **file_format** (*str*) – Desired image format (if not specified, this will be derived from the file extension of `file_path`)
- **capacity** – TODO what's the expected format?
- **contents** (*list*) – List of file paths to package into the created image. If not specified, the image will be left blank and unformatted.

get_checksum (*file_path*, *checksum_type*)

Get the checksum of the given file.

Parameters

- **file_path** (*str*) – Path to file to checksum
- **checksum_type** (*str*) – Supported values are 'md5' and 'sha1'.

Returns String containing hexadecimal file checksum

get_disk_capacity (*file_path*)

Get the storage capacity of the given disk image.

Parameters **file_path** (*str*) – Path to disk image file to inspect

Returns Disk capacity, in bytes

get_disk_format (*file_path*)

Get the disk image format of the given file.

Warning: If `file_path` refers to a file which is not a disk image at all, this function will return ('raw', None).

Parameters **file_path** (*str*) – Path to disk image file to inspect.

Returns

(*format*, *subformat*)

- *format* may be 'vmdk', 'raw', or 'qcow2'
- *subformat* may be None, or various strings for 'vmdk' files.

get_ovftool_version ()

Get installed ovftool version as a `StrictVersion` object.

Returns `StrictVersion` instance

Raises `HelperNotFoundError` if `ovftool` is not found.

get_qemu_img_version ()

Get installed qemu-img version as a `StrictVersion` object.

Returns `StrictVersion` instance

Raises `HelperNotFoundError` if `qemu-img` is not found.

validate_ovf_for_esxi (*ovf_file*)

Use VMware's `ovftool` program to validate an OVF or OVA.

This checks the file against the OVF standard and any VMware-specific requirements.

Parameters **ovf_file** (*str*) – File to validate

Returns Output from `ovftool`

Raises

- **HelperNotFoundError** – if `ovftool` is not found.
- **HelperError** – if `ovftool` regards the file as invalid

6.3.3 COT.platforms module

Handles behavior that varies between guest platforms.

Classes

<code>GenericPlatform</code>	Generic class for operations that depend on guest platform.
<code>CSR1000V</code>	Platform-specific logic for Cisco CSR1000V platform.
<code>IOSv</code>	Platform-specific logic for Cisco IOSv.
<code>IOSXRv</code>	Platform-specific logic for Cisco IOS XRv platform.
<code>IOSXRvRP</code>	Platform-specific logic for Cisco IOS XRv HA-capable RP.
<code>IOSXRvLC</code>	Platform-specific logic for Cisco IOS XRv line card.
<code>NXOSv</code>	Platform-specific logic for Cisco NX-OSv (Titanium).

class `GenericPlatform`

Bases: `object`

Generic class for operations that depend on guest platform.

To be used whenever the guest is unrecognized or does not need special handling.

classmethod `controller_type_for_device(device_type)`

Get the default controller type for the given device type.

classmethod `guess_nic_name(nic_number)`

Guess the name of the Nth NIC for this platform.

Note that this counts from 1, not from 0!

classmethod `valid_list_only(desc, val, supported_list)`

Error if the given value is not an item in the provided list.

classmethod `validate_cpu_count(cpus)`

Throw an error if the number of CPUs is not a supported value.

classmethod `validate_memory_amount(megabytes)`

Throw an error if the amount of RAM is not supported.

classmethod `validate_nic_count(count)`

Throw an error if the number of NICs is not supported.

classmethod `validate_nic_type(type_string)`

Throw an error if the NIC type string is not supported.

classmethod `validate_serial_count(count)`

Throw an error if the number of serial ports is not supported.

BOOTSTRAP_DISK_TYPE = 'cdrom'

CONFIG_TEXT_FILE = 'config.txt'

LITERAL_CLI_STRING = 'config'

PLATFORM_NAME = '(unrecognized platform, generic)'

SECONDARY_CONFIG_TEXT_FILE = None

class CSR1000V

Bases: `COT.platforms.GenericPlatform`

Platform-specific logic for Cisco CSR1000V platform.

classmethod `controller_type_for_device` (*device_type*)
CSR1000V uses SCSI for hard disks and IDE for CD-ROMs.

classmethod `guess_nic_name` (*nic_number*)
GigabitEthernet1, GigabitEthernet2, etc.

Warning: In all current CSR releases, NIC names start at “GigabitEthernet1”. Some early versions started at “GigabitEthernet0” but we don’t support that.

classmethod `validate_cpu_count` (*cpus*)
CSR1000V supports 1, 2, or 4 CPUs.

classmethod `validate_memory_amount` (*megabytes*)
Minimum 2.5 GB, max 8 GB.

classmethod `validate_nic_count` (*count*)
CSR1000V requires 3 NICs and supports up to 26.

classmethod `validate_serial_count` (*count*)
CSR1000V supports 0-2 serial ports.

CONFIG_TEXT_FILE = ‘iosxe_config.txt’

LITERAL_CLI_STRING = ‘ios-config’

PLATFORM_NAME = ‘Cisco CSR1000V’

class IOSv

Bases: `COT.platforms.GenericPlatform`

Platform-specific logic for Cisco IOSv.

classmethod `guess_nic_name` (*nic_number*)
GigabitEthernet0/0, GigabitEthernet0/1, etc.

classmethod `validate_cpu_count` (*cpus*)
IOSv only supports a single CPU.

classmethod `validate_memory_amount` (*megabytes*)
IOSv has minimum 192 MB (with minimal feature set), max 3 GB.

classmethod `validate_nic_count` (*count*)
IOSv supports up to 16 NICs.

classmethod `validate_nic_type` (*type_string*)
IOSv only supports E1000 NICs.

classmethod `validate_serial_count` (*count*)
IOSv requires 1-2 serial ports.

BOOTSTRAP_DISK_TYPE = ‘harddisk’

CONFIG_TEXT_FILE = ‘ios_config.txt’

LITERAL_CLI_STRING = None

PLATFORM_NAME = ‘Cisco IOSv’

class IOSXRv

Bases: `COT.platforms.GenericPlatform`

Platform-specific logic for Cisco IOS XRv platform.

classmethod `guess_nic_name` (*nic_number*)

MgmtEth0/0/CPU0/0, GigabitEthernet0/0/0/0, Gig0/0/0/1, etc.

classmethod `validate_cpu_count` (*cpus*)

IOS XRv supports 1-8 CPUs.

classmethod `validate_memory_amount` (*megabytes*)

Minimum 3 GB, max 8 GB of RAM.

classmethod `validate_nic_count` (*count*)

IOS XRv requires at least one NIC.

classmethod `validate_nic_type` (*type_string*)

IOS XRv supports E1000 and virtio NICs.

classmethod `validate_serial_count` (*count*)

IOS XRv supports 1-4 serial ports.

CONFIG_TEXT_FILE = 'iosxr_config.txt'

LITERAL_CLI_STRING = None

PLATFORM_NAME = 'Cisco IOS XRv'

SECONDARY_CONFIG_TEXT_FILE = 'iosxr_config_admin.txt'

class IOSXRvRP

Bases: `COT.platforms.IOSXRv`

Platform-specific logic for Cisco IOS XRv HA-capable RP.

classmethod `guess_nic_name` (*nic_number*)

Fabric and management only.

- fabric

- MgmtEth0/{SLOT}/CPU0/0

classmethod `validate_nic_count` (*count*)

Fabric plus an optional management NIC.

PLATFORM_NAME = 'Cisco IOS XRv route processor card'

class IOSXRvLC

Bases: `COT.platforms.IOSXRv`

Platform-specific logic for Cisco IOS XRv line card.

classmethod `guess_nic_name` (*nic_number*)

Fabric interface plus slot-appropriate GigabitEthernet interfaces.

- fabric

- GigabitEthernet0/{SLOT}/0/0

- GigabitEthernet0/{SLOT}/0/1

- etc.

classmethod `validate_serial_count` (*count*)

No serial ports are needed but up to 4 can be used for debugging.

```
CONFIG_TEXT_FILE = None
PLATFORM_NAME = 'Cisco IOS XRv line card'
SECONDARY_CONFIG_TEXT_FILE = None

class NXOSv
    Bases: COT.platforms.GenericPlatform
    Platform-specific logic for Cisco NX-OSv (Titanium).

    classmethod guess_nic_name (nic_number)
        NX-OSv names its NICs a bit interestingly...

        •mgmt0
        •Ethernet2/1
        •Ethernet2/2
        •...
        •Ethernet2/48
        •Ethernet3/1
        •Ethernet3/2
        •...

    classmethod validate_cpu_count (cpus)
        NX-OSv requires 1-8 CPUs.

    classmethod validate_memory_amount (megabytes)
        NX-OSv requires 2-8 GB of RAM.

    classmethod validate_nic_type (type_string)
        NX-OSv supports only E1000 and virtio NICs.

    classmethod validate_serial_count (count)
        NX-OSv requires 1-2 serial ports.

    CONFIG_TEXT_FILE = 'nxos_config.txt'
    LITERAL_CLI_STRING = None
    PLATFORM_NAME = 'Cisco NX-OSv'
```

6.4 User interface modules

<code>COT.ui_shared</code>	Abstract user interface superclass.
<code>COT.cli</code>	CLI entry point for the Common OVF Tool (COT) suite.

6.4.1 COT.ui_shared module

Abstract user interface superclass.

```
class UI (force=False)
    Bases: object
    Abstract user interface functionality.
```

Can also be used in test code as a stub that autoconfirms everything.

confirm (*prompt*)

Prompt user to confirm the requested operation.

Auto-accepts if `force` is set to `True`.

Warning: This stub implementation does not actually interact with the user, but instead returns `default_confirm_response`. Subclasses should override this method.

Parameters `prompt` (*str*) – Message to prompt the user with

Returns `True` (user confirms acceptance) or `False` (user declines)

confirm_or_die (*prompt*)

If the user doesn't agree, abort the program.

A simple wrapper for `confirm()` that calls `sys.exit()` if `confirm()` returns `False`.

fill_examples (*example_list*)

Pretty-print a set of usage examples.

Parameters `example_list` (*list*) – List of (example, description) tuples.

Raises `NotImplementedError` Must be implemented by a subclass.

fill_usage (*subcommand*, *usage_list*)

Pretty-print a list of usage strings.

Parameters

- **subcommand** (*str*) – Subcommand name/keyword
- **usage_list** (*list*) – List of usage strings for this subcommand.

Returns `String` containing all usage strings, each appropriately wrapped to the `terminal_width()` value.

get_input (*prompt*, *default_value*)

Prompt the user to enter a string.

Auto-inputs the `default_value` if `force` is set to `True`.

Warning: This stub implementation does not actually interact with the user, but instead always returns `default_value`. Subclasses should override this method.

Parameters

- **prompt** (*str*) – Message to prompt the user with
- **default_value** (*str*) – Default value to input if the user simply hits Enter without entering a value, or if `force`.

Returns `Input value`

Return type `str`

get_password (*username*, *host*)

Get password string from the user.

Warning: This stub implementation does not actually interact with the user, but instead always returns `"passwd"`. Subclasses should override this method.

Parameters

- **username** (*str*) – Username the password is associated with
- **host** (*str*) – Host the password is associated with

terminal_width ()

Get the width of the terminal in columns.

default_confirm_response = None

Knob for API testing, sets the default response to confirm().

force = None

Whether to automatically select the default value in all cases.

(As opposed to interactively prompting the user.)

6.4.2 COT.cli module

CLI entry point for the Common OVF Tool (COT) suite.

Classes

CLI	Command-line user interface for COT.
-----	--------------------------------------

class CLI

Bases: `COT.ui_shared.UI`

Command-line user interface for COT.

<code>confirm</code>	Prompt user to confirm the requested operation.
<code>create_parser</code>	Create <code>parser</code> object for global <code>cot</code> command.
<code>create_subparsers</code>	Populate the CLI sub-parsers for all known submodules.
<code>fill_examples</code>	Pretty-print a set of usage examples.
<code>fill_usage</code>	Pretty-print a list of usage strings for a COT subcommand.
<code>formatter</code>	Create formatter for log output.
<code>get_input</code>	Prompt the user to enter a string.
<code>get_password</code>	Get password string from the user.
<code>main</code>	Main worker function for COT when invoked from the CLI.
<code>parse_args</code>	Parse the given CLI arguments into a namespace object.
<code>run</code>	Parse the given CLI args then run.
<code>set_verbosity</code>	Enable logging and/or change the logging verbosity level.
<code>terminal_width</code>	Get the width of the terminal in columns.

confirm (*prompt*)

Prompt user to confirm the requested operation.

Auto-accepts if `force` is set to `True`.

Parameters **prompt** (*str*) – Message to prompt the user with

Returns `True` (user confirms acceptance) or `False` (user declines)

create_parser ()

Create `parser` object for global `cot` command.

Includes a number of globally applicable CLI options.

create_subparsers ()

Populate the CLI sub-parsers for all known submodules.

Creates an instance of each `COTGenericSubmodule` subclass, then calls `create_subparser()` for each.

fill_examples (*example_list*)

Pretty-print a set of usage examples.

```
>>> fill_examples([
...     ('cot deploy foo.ova esxi 192.0.2.100 -u admin -p admin'
...     ' -n test_vm',
...     "Deploy to vSphere/ESXi server 192.0.2.100 with credentials"
...     " admin/admin, creating a VM named 'test_vm' from foo.ova."),
...     ('cot deploy foo.ova esxi 192.0.2.100 -u admin -c 1CPU-2.5GB',
...     "Deploy to vSphere/ESXi server 192.0.2.100, with username"
...     " admin (prompting the user to input a password at runtime)",
...     " creating a VM based on profile '1CPU-2.5GB' in foo.ova.")
... ])
```

Examples:

```
cot deploy foo.ova esxi 192.0.2.100 -u admin -p admin \
    -n test_vm
Deploy to vSphere/ESXi server 192.0.2.100 with
credentials admin/admin, creating a VM named 'test_vm'
from foo.ova.

cot deploy foo.ova esxi 192.0.2.100 -u admin \
    -c 1CPU-2.5GB
Deploy to vSphere/ESXi server 192.0.2.100, with
username admin (prompting the user to input a password
at runtime), creating a VM based on profile
'1CPU-2.5GB' in foo.ova.
```

Parameters `example_list` (*list*) – List of (`cli_example`, `example_description`) tuples.

Returns Examples wrapped appropriately to the `terminal_width()` value. CLI examples will be wrapped with backslashes and a hanging indent.

fill_usage (*subcommand*, *usage_list*)

Pretty-print a list of usage strings for a COT subcommand.

Automatically prepends a `cot subcommand --help` usage string to the provided list.

```
>>> fill_usage('add-file', ["FILE PACKAGE [-o OUTPUT] [-f FILE_ID]"])
cot add-file --help
cot add-file FILE PACKAGE [-o OUTPUT]
                        [-f FILE_ID]
```

Parameters

- **subcommand** (*str*) – Subcommand name/keyword
- **usage_list** (*list*) – List of usage strings for this subcommand.

Returns String containing all usage strings, each appropriately wrapped to the `terminal_width()` value.

formatter (*verbosity=20*)

Create formatter for log output.

We offer different (more verbose) formatting when debugging is enabled, hence this need.

Parameters `verbosity` – Logging level as defined by logging.

Returns Formatter object for use with logging.

Return type instance of `colorlog.ColoredFormatter`

get_input (*prompt*, *default_value*)

Prompt the user to enter a string.

Auto-inputs the `default_value` if `force` is set to `True`.

Parameters

- **prompt** (*str*) – Message to prompt the user with
- **default_value** (*str*) – Default value to input if the user simply hits Enter without entering a value, or if `force`.

Returns Input value

Return type `str`

get_password (*username*, *host*)

Get password string from the user.

Parameters

- **username** (*str*) – Username the password is associated with
- **host** (*str*) – Host the password is associated with

Raises `InvalidInputError` if `force` is `True` (as there is no “default” password value)

main (*args*)

Main worker function for COT when invoked from the CLI.

- Calls `set_verbosity()` with the appropriate verbosity level derived from the args.
- Looks up the appropriate `COTGenericSubmodule` instance corresponding to the subcommand that was invoked.
- Converts `args` to a dict and calls `set_value()` for each arg/value in the dict.
- Calls `run()` followed by `finished()`.
- Catches various exceptions and handles them appropriately.

Parameters `args` – Parser namespace object returned from `parse_args()`.

Return type `int`

Returns

Exit code for the COT executable.

- 0 on successful completion
- 1 on runtime error
- 2 on input error (parser error, `InvalidInputError`, etc.)

parse_args (*argv*)

Parse the given CLI arguments into a namespace object.

Parameters `argv` (*list*) – List of CLI arguments, not including `argv0`

Returns Parser namespace object

run (*argv*)

Parse the given CLI args then run.

Calls `parse_args()` followed by `main()`.

Parameters *argv* (*list*) – The CLI argv value (not including argv[0])

Returns Return code from `main()`

set_verbosity (*level*)

Enable logging and/or change the logging verbosity level.

Will call `formatter()` and associate the resulting formatter with logging.

Parameters *level* – Logging level as defined by `logging`

terminal_width ()

Get the width of the terminal in columns.

main ()

Launch COT from the CLI.

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